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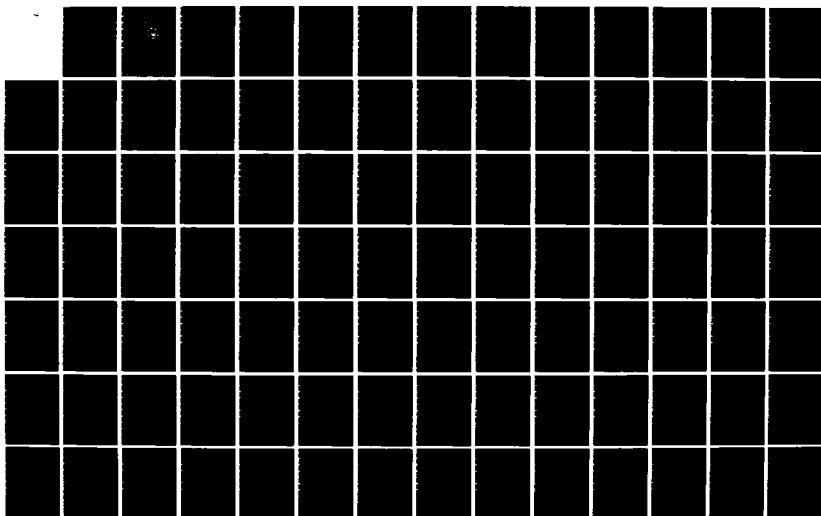
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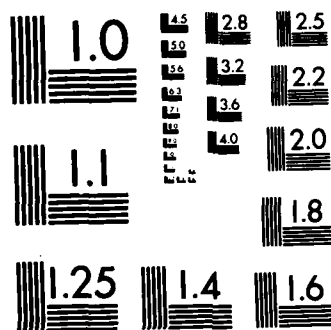
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INVESTIGATION OF NON-LINEAR ESTIMATION  
OF NATURAL RESONANCES  
IN TARGET IDENTIFICATION

by

Choong Y. Chong

December 1983

Thesis Advisor:

M. A. Morgan

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INVESTIGATION OF NON-LINEAR ESTIMATION  
OF NATURAL RESONANCES  
IN TARGET IDENTIFICATION

by

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## ABSTRACT

This investigation considers a non-linear technique for extracting natural resonances from transient electromagnetic scattering responses of radar targets. These natural resonances represent the complex poles of the target's transfer function in the Laplace transform  $s$ -plane. The advantage of their use in identification is their dependence only upon the geometry and composition of the target and not upon the aspect and polarization of the incident signal.

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## I. INTRODUCTION

This investigation considers a non-linear technique for extracting natural resonances from transient electromagnetic scattering responses of radar targets. These natural resonances represent the complex poles of the target's transfer function in the Laplace transform  $s$ -plane. The advantage of their use in identification is their dependence only upon the geometry and composition of the target and not upon the aspect and polarization of the incident signal.

Concepts and methodologies evolving from this idea have been developed based on the Singularity Expansion Method (SEM) by Baum [Ref. 1] in which the location of  $s$ -plane singularities characterizes a target. The direct extraction of poles (and residues) from the complex impulse response was initially attempted by Main and Moffat [Ref. 2]. These two early references spawned the idea of using natural resonances as the basis of non-cooperative target recognition (NCTR).

The application of the Householder orthogonalization method using a successive orthogonalization process and the eigenvalue method, that finds eigenvectors and eigenvalues, can determine the number and value of poles from the traditional transient signal model of a scatterer if there is a sufficiently low level of noise in the data [Ref. 3]. But both methods show poor quality of performance if we apply

them to the new signal model, even were there is no noise assumed in the signal data. This new signal model, which represents the electromagnetic scattering transient response of actual targets, was recently derived by Morgan [Ref. 4].

As considered in [Ref. 2], the relationship between a scattering target and the singularities being extracted from the natural complex resonance signal has been emphasized in the context of the number of poles and the accuracy of poles to ensure the unique relationship between an object and its image. Namely, the accuracy of pole extraction plays an important part in setting baselines to check consistency between a received signal and a set of singularities. Also, [Ref. 2] describes the modeling problem of a signal such that we express a transient response signal in terms of complex exponentials and the way it can be manipulated by Prony's algorithm. This signal model (termed here as the traditional model), was found not to represent the actual transient signal in the recent work by Davenport [Ref. 5]. In 1982, Manilha, in his work, commented that the new signal model might be partitioned into "early time signal" and "late time signal", each of which characterize the signal by the time instant at which the traditional model can be acceptable or not [Ref. 3]. This effort considers the development of a method that is capable of handling the "early time" whose time varying residues of exponentials do not become constant until the excitation of the incident field disappears. Such a signal

can not be adequately or accurately modeled by the traditional model.

It is the intention of this work to investigate a method that can handle the "early time signal" and show "Robustness" under relatively heavy noise pollution as well as improving the accuracy of the poles we are interested in evaluating. A non-linear parameter optimization approach, through the modified least-squares minimization method, has been tried. In particular, we have been interested in evaluating its performance in improving the accuracy of the poles extracted. The non-linear parameter optimization approach using iterations has contributed to improvement of accuracy and showed the possibility of application to the "early time signal" as was the final goal. We define the "new signal model" as a causal connection of the "early time signal" and "late time signal" throughout this paper. The new signal model will be presented in Chapter II, with both the description of the transient response mechanism and the way in which the signal model is constructed through the transient response mechanism. Chapter III briefly describes the problems associated with the traditional model, and with many of the current extraction methods in existence. Chapter IV is devoted to the description of the non-linear parameter optimization through a modified least-squares method and the way in which the algorithm is implemented. Chapter V presents test results of an attempt to use this approach for pole extraction and its performance characteristics. Chapter VI contains a summary

of the simulation results, the problems encountered, the potential problems expected, and the possibility of application of this method.

Computations were performed using the IBM 3033 system at the Naval Postgraduate School. The testing of concept feasibility was the major impetus behind this effort, with concerns for practical implementation in a "real-time" environment left for subsequent study. Considerations to the processing speed will not be addressed in this thesis. All the calculations were done in a double precision environment.

## II. SCATTERING TRANSIENT RESPONSE SYSTEM

### A. TRANSIENT RESPONSE MECHANISM

An electromagnetic wave incident upon a scattering body forces currents to be distributed such that Maxwell's equations and the corresponding boundary conditions are satisfied. These induced currents produce a scattered field that can be defined at any coordinate in free space if the expressions for those currents are made correctly. Changes in the angle of incidence, the incident wave shape, the polarization mode, and the target geometry and composition affect the results of the evaluation of the scattered transient response.

Basically, the singularities uniquely characterize a scatterer by their number and locations. The corresponding residues, which are interpreted as the weights of these poles, either can be viewed in the frequency domain or in the time domain.

As shown in [Ref. 3], equation (2.1) represents the form of the scattered signal impulse response of the target, in digital form

$$H(k) = H_0(kT) + \sum_{m=1}^{\infty} H_k \exp(kS_m T) \quad (2.1)$$

where  $H_0(t) = 0$  for  $t \geq T0$ ,  $T$  is the sampling interval and the infinite sum represents the natural resonance response with complex  $S_m = \sigma_m + j\omega_m$  in the left-half plane. The poles constitute the parameters for NCTR of an object. The process

of extracting those parameters from the impulse response first collects the data points within a finite time period (time window).

The data collected is represented using equation (2.1) and equation (2.3) which partitions the signal into "early time" and "late time" components.

$$X(k) = \sum_{k=0}^{\infty} H(k) * \sum_{k=0}^{M-1} I(k) \quad (2.2)$$

$$X(k) = \sum_{k=0}^{T\theta-1} H(k) * \sum_{k=0}^{M-1} I(k) + \sum_{k=T\theta}^{\infty} H(k) * \sum_{k=\theta}^{M-1} I(k) \quad (2.3)$$

early time data

late time data

where  $I(k)$  is the incident wave at  $t = kT$

$T$  is sampling interval in time.

We can write the equation (2.3) in the form of equation (2.4) or (2.5). Both of these expressions display the essence of the new signal model which will be discussed in the next section.

$$X(k) = \sum_{n=1}^N A_n(k) \exp(S_n k) \quad (2.4)$$

where  $A_n(k) = A_n$  for  $k \geq T\theta$

$$X(k) = E(k) + \sum_{n=1}^N A_n \exp(S_n k) \quad (2.5)$$

where  $E(k) = \theta$  for  $k \geq T\theta$

and  $A_n$  is constant for all  $k$



$T_0$  is the point at which the late time signal starts, so we consider that a time window might contain the data points ranging from the one before  $T_0$  to that after  $T_0$ . If we perform processing on a data window containing the data points which were from that early time region, we may lose some of the poles of natural resonance what are likely to be seen in the late time region. The data points after  $K_0$  presumably has all the information regarding poles, even though there are some extra poles that may be discriminated from the natural poles. These extra poles are introduced by the result of noise with relatively low SNR. Also, there is another risk to lose the natural poles having very high damping coefficients. There is no effective method yet found to compromise on having the point in which we can see all the poles with less extra poles under the higher SNR condition.

Meanwhile, the discrimination of  $E(k)$  appears to us as the quantity to be handled to give improvement in accuracy of the natural poles. The next section describes the new signal model based on these aspects and the transient response mechanism.

#### B. IMPULSE RESPONSE SIGNAL MODEL

The late time impulse response can be expressed as a summation of exponentially damped sinusoids as in equation (2.6).

$$x_a(k) = \sum_{n=1}^N A_n \exp(S_n k), \quad k=0, T, 2T, \dots, (M-1)T \quad (2.6)$$

where  $T = \Delta t$ , and  $M$  is the number of sampling points. The signal model expressed in equation (2.6) is valid after the incident wave has completely illuminated a target and no forced response remains.

As the mechanism of a transient response system is strictly governed by the physics and orientation of the target and the attributes of the incident wave, we can write the equation (2.7) as an implicit form of equation (2.2), assuming we strike the target with a plane wave impulse.

$$X_b(k) = \sum_{k=0}^{\infty} H(k) \cdot \sum_{k=0}^{T0-1} [u(k) - u(k-T0)] \quad (2.7)$$

Combining both equations (2.6) and (2.7), equation (2.9) would be sufficient if we assume  $N$  poles are present.

$$\begin{aligned} X(k) &= X_a(k) + X_b(k) \\ X(k) &= \sum_{k=0}^{\infty} H(k) \cdot \sum_{k=0}^{T0-1} [u(k) - u(k-T0)] \\ &+ A_n \exp(S_n k), k=0, T, 2T, \dots, (M-1)T \end{aligned} \quad (2.9)$$

We call the impulse response signal model, in the form of equation (2.9), an implicit form of the new signal model. A simpler form of equation (2.9) can be either of equations (2.10) or (2.11).

$$X(k) = E(k) + \sum_{n=1}^N A_n \exp(S_n k) \quad (2.10)$$

$$X(k) = \sum_{n=1}^N A_n(k) \exp(S_n k) \quad (2.11)$$

where  $A_n(k) = A_n$ , for  $k \geq T\theta$

In equation (2.1), the residues are time-varying until the time at which the augmented function  $E(k)$  in equation (2.10) becomes zero. Thereafter the  $A_n(k) = A_n$  (constant).

To begin with equation (2.10), it is necessary to define a new independent variable as a parameter whose time behavior is not predictable along the positive time axis. It is convenient to define this as a set of variables. By regarding them as independent, the equation (2.11) would be in the form of the equation (2.12) in the discrete digital data processing sense.

$$X(k) = E(k) + \sum_{n=1}^N A_n \exp(S_n k) \quad (2.12)$$

$$X(k) = \sum_{n=1}^{T\theta-1} e_n(k) + \sum_{n=1}^N A_n \exp(S_n k) \quad (2.13)$$

assuming  $e_n(k) = E_n \delta(k-n)$

The equation (2.14) is expressed in terms of a positive counting sequence in  $k$ . As in the equation, we might evaluate the equation (2.13) if we know the exact number of poles. But we know that it is impossible because we are in the region of the early time. So we write the equation (2.14) as a time shifted version such as the equation that has meaning from the observability viewpoint.

$$X(k) = \sum_{n=1}^{T\theta-1} e_n(k) + \sum_{n=1}^N A_n \exp(S_n k) \quad (2.14)$$

where  $k=T\theta+m, T\theta+m-1, \dots, T\theta+1, T\theta, T\theta-1, \dots, T\theta, \theta$   
for  $m \geq 0$

Here, the examples of the new signal model are presented in Appendix C, in the form of a decomposed signal. This synthetically generated signal is written in terms of  $e_n(k)$ 's and the sum of exponentials. In Chapter V, we present the decomposed signal from the synthetically generated data signal and that obtained by constructing the  $E(k)$  as the results of the non-linear parameter optimization processing.

### C. NOISE

White Gaussian noise is assumed throughout this work. By introducing the noise into the new impulse signal model, we call the following equation the modeling function of a transient response system and the complete and general form of the new signal model.

$$X(k) = N(k) + \sum_{n=1}^{\infty} e_n(k) + \sum_{n=1}^N A_n \exp(S_n k) \quad (2.15)$$

### III. PROBLEMS WITH THE TRADITIONAL METHODS

In this chapter, a brief description of problems with the classic Prony's method, the Householder orthogonalization technique and the Eigenvalue method are provided. Each of these methods computes the location of poles in the s-plane but only the last two methods can estimate the number of poles prior to the discrimination of the poles.

#### A. PRONY'S ALGORITHM

Equation (2.3) is interpreted as the following difference equation assigning the values of the real part of the signal at specified sampling points in its left side of the expression.

$$\begin{aligned} X(0) &= \sum_{n=1}^N A_n \\ X(k) &= \sum_{n=1}^N A_n z_n^k \\ &\vdots \\ X((M-1)k) &= \sum_{n=1}^N A_n z_n^{(M-1)k} \end{aligned} \tag{3.1}$$

And a polynomial equation (3.2) that has the same roots  $z_n$

$$\sum_{n=1}^N a_n z^n = 0 \tag{3.2}$$

can be combined with equation (3.1) to yield the Prony's difference equation in the form of equation (3.3)

$$\sum_{n=1}^N a_n X(n+k) = 0, \quad \text{for } k=0, T, 2T, \dots, (M-1)T \quad (3.3)$$

Then, we write equation (3.4) from equation (3.3) as

$$\sum_{n=1}^N a_n X(n+k) = \sum_{n=1}^{N-1} a_n X(n+k) + a_N x(n+k) = 0 \quad (3.4)$$

Using matrix notation, the equation (3.3) may be written as equation (3.5) or (3.6).

$$\sum_{n=1}^{N-1} a_n X(n+k) = -a_N X(n+k) \quad (3.5)$$

Let  $a_N = 1$ , then equation (3.5) becomes as

$$X_{N-1} A_{N-1} = x_N \quad (3.6)$$

where  $X_{N-1}$  is  $N$  by  $N$  circulant matrix of sampled data

$A_{N-1}$  is  $N$  by 1 Prony's coefficients matrix

$x_N$  is  $N$  by 1 row matrix of sampled data set

$$[X_{N,N+1}, \dots, X_{2N-1}]$$

The Prony's coefficient  $a_n$ 's are to be calculated by making use of the characteristics of the circulant matrix  $X$ .

$$A_{N-1} = (A_{N-1} X_{N-1})^{-1} A_{N-1} x_N \quad (3.7)$$

As described in the above, this method can be applied after the number of poles are known to us, then the value of the  $S_n$ 's are to be found from the equation (3.8).

$$S_n = \text{LN}(Z_n)/k, \text{ for } k \geq 2N \quad (3.8)$$

#### B. HOUSEHOLDER ORTHOGONALIZATION METHOD

A general expression of equation (3.2) may be represented by equation (3.9) assuming the number of poles are not known.

$$a_0 + a_1 z^1 + \dots + a_{N'} z^{N'} = 0 \quad (3.9)$$

where  $N'$  is the unknown variable

Then, the equation (3.9) is to be satisfied under the condition that there are enough sampled data points  $m \geq 2N$ .

$$a_0 x_0 + a_1 x_1 + \dots + a_{N'} x_{N'} = 0 \quad (3.10)$$

where the  $N$  by  $1$  sampled data matrix is defined as

$$x_i = [X(i), X(i+2), \dots, X(M-N-i+1)]$$

Application of the successive orthogonalization through the Gram-Schmit process would produce the orthogonal vector set.

$$O = \{o_0, o_1, \dots, o_{N'}\}$$

$$\text{where } o_n = x_n - \sum_{i=0}^{n-1} \langle x_n, o_i \rangle o_i \quad (3.11)$$

If we set the  $o_0$  to be  $1$ , then the  $N$  by  $1$   $x_n$  matrix is going to be in the form of equation (3.11).

$$x_n = o_n + \sum_{i=0}^{n-1} \langle x_n, o_i \rangle o_i \quad (3.12)$$

So that the equation (3.12) holds as  $X=OM$ . In the above,  $M$  is the  $2$ -D matrix of multiplication factors whose diagonal

elements are all 1's. Here, an orthogonal vector  $o_1$  makes the corresponding data set  $x_i$  to be orthogonal to all the previous vectors  $x_0 - x_{i-1}$ . If we have had all the  $x$  vectors during  $i-1$  times of successive orthogonalization process such that there is a non-zero orthogonal vector. We have to receive continuously the next data set  $x_{i+1}$  and check whether the orthogonal vector in the next step is zero or under a given threshold. If it vanishes, we can say that we have  $(i-1)$  poles. Our test against noise polluted data signal using the Householder method showed the inability of handling the early time signal as well as the data being heavily polluted.

### C. EIGENVALUE METHOD

Again, from the equation (3.10), we can rewrite this equation as in the form of equation (3.14).

$$X_N Z_N = 0 \quad (3.14)$$

$$\text{where } X_N = [x_0 | x_1 | \dots | x_N]$$

The eigenvector can be derived from the equation (3.15) by doing some mathematical manipulations of equation (3.14).

$$X_N^T X_N A_N = X_N^T X_N E_N = 0$$

From this equation, we find the eigenvalues correspond to eigenvectors to see if there is any eigenvalue approaching zero. If there is one zero or under threshold, we also consider the number of poles as  $N'-1$ . Even both the



Householder orthogonalization method and the Eigenvalue method can provide the means of calculating the number of poles, their algorithm (tending to fit the data points to the traditional signal model) showed the lack of generality.

#### IV. NON-LINEAR PARAMETER OPTIMIZATION APPROACH

##### A. INTRODUCTION

In 1963, Marquardt suggested an algorithm for the least-squares estimation of non-linear parameters [Ref. 6] when highly accurate parameter values are required. As we can see in the signal model in equation (2.14), that new signal model has multiple parameters that are functions of time. Here, we rewrite that equation again in the form of equation (4.1).

$$X(k) = N(k) + \sum_{n=k}^{T\theta-1} e_n(k) + \sum_{n=1}^N A_n \exp(S_n k) \quad (4.1)$$

where  $e_n(k) = 0$ , for  $k \geq T\theta$

We are not interested in the value of  $e_n(k)$  itself, but include their estimations in order to contribute to the accuracy of  $S_n$ 's and  $A_n$ 's.

In other words, the extrapolation of the sum of exponentials, which is assumed to have all the poles, to points in the early time region may provide more accurate poles and residues simultaneously.

The major advantage is the fact that we can make use of the high SNR data signal in the early time region with the basic information of poles that were derived in the late time region.

We will be processing on a data window whose vector length is to be increased one by one by moving the first element of that vector toward the time-origin point. The optimization process evaluates the normal equation to find the local optimized set and finds the global optimized set as its final goal.

Let us define an ERROR function as in equation (4.3)

$$\text{ERROR}\{A_n, S_n, E(k)\} = \sum_{n=1}^{N-1} [X'(k) - X(k)]^2 \quad (4.3)$$

where  $X'(k)$  is a measured data point

To have minimized the least-squares error at every instant of measured time, the ERROR function has to be minimized by obtaining the global set of parameters being optimized. We also can write equation (4.3) in a more concrete manner as in equation (4.4).

$$\text{ERROR}\{X\} = \sum_{k=0}^{M-1} [X'(k) - X(k)]^2 = \sum_{k=0}^{M-1} e(k)_n^2 \quad (4.4)$$

where  $X = [E(k), A_n, S_n]$

Non-linear parameters such as  $e_n(k)$  must be optimized in a way such that the more accurate values of  $S_n$  have to be calculated as we increase the number of non-linear parameters  $e_n$ . Users may define the numbers of parameter  $e_n$ 's that are at least equal to or greater than the number of data points in the early time region. Now it is our task to find out the optimized value of  $A_n, S_n$ , and  $e_n$  through optimization processing, either in the global sense as it is represented in the equation (4.5) or using the normal equation (4.6).

$$\partial \text{ERROR}(X) / \partial X = 0 \quad (4.5)$$

$$\partial e_n(k) / \partial X(k) = 0 \quad (4.6)$$

where  $k=0, T, 2T \dots, (M-1)K$   
 $n=1, 2, \dots, N$

With using the normal equation, as it is shown in the (4.6), a global set of non-linear set of parameters can be obtained through an iterative evaluation and fitting process. In our simulation work, the modified least-squares method was the basis of the equation (4.6).

#### B. THE MODIFIED LEAST-SQUARES METHOD

The error function is rewritten as in the expression of the equation (4.7).

$$\text{ERROR}\{k, x\} = X'(k) - X(k, x_n^k) \quad (4.7)$$

where  $X'(k)$  is the  $k$ -th sampled data

$X(k, x)$  is the model function

$x_n^k$  is a vector containing the  $k$ -th sampled

Let us define  $x_n^0$  to be an initial estimated value of  $x$ , then a sequence of approximations to the optimized value is to be generated by the equation (4.8).

$$x^{m+1} = x^m - [a_m D_m + J_m^T J_m]^{-1} J_m^T \text{ERROR}(x^m) \quad (4.8)$$

where  $J_m$  is the numerical Jacobian matrix evaluated

$m$  is iteration number of successive optimization

$D_m$  is a diagonal matrix equal to the diagonal of

$$J_m^T J_m$$

$a_m$  is a Marquardt parameter

The number of total iterations can be controlled by the threshold which is defined as in the equation (4.9).

$$d = x^{m+1} - x^m \quad (4.9)$$

## V. TEST RESULTS AND PERFORMANCE EVALUATION

### A. INTRODUCTION

In order to establish the ability of the program listed in Appendix B to extract the poles and residues correctly, three different simulated signals, each of which is polluted with infinite, 30 dB and 15 dB SNR, were created by the synthetic signal data generation routine. These 3 sets of signal data were chosen to span a range of possible situations.

In the context of the transient signals and additive stationary Gaussian noise being used, the definition of SNR is in terms of a ratio of energy quantities intergrated over the entire 20 nsec time window.

TABLE I  
SIMULATED SIGNAL 1

<u>RESIDUES</u>	<u>POLES</u> (Nep. GHZ)
$1.0 + i1.0$	$-1.0 + i1.0$
$1.0 - i1.0$	$-1.0 - i1.0$

Simulated signal 2 consists of 2 sets of pairs of complex conjugate poles and residues, which is an extrapolation of the simulated signal 1, using its parameters. Simulated signal 3 has 3 sets of pole-residue pairs, extrapolating from signal 2.

There are 5 options in the signal generation program in choosing a particular function of  $E(k)$ . In this simulation work, a trapezoidal wave form of  $E(k)$  was used with  $T_0 = 0.42$  nsec. So that the unknown parameters that are to be augmented

at every processing step will be a maximum of 10 plus 4 times the number of poles at the final processing stage, when we have 512 data points within a 20 nsec time window.

TABLE II  
SIMULATED SIGNAL 2

<u>RESIDUES</u>	<u>POLES</u> (Nep.      GHZ)
$1.0 + i1.0$	$-1.0 + i1.0$
$1.0 - i1.0$	$-1.0 - i1.0$
$0.5 + i0.5$	$-2.0 + i2.0$
$0.5 + i0.5$	$-2.0 - j2.0$

TABLE III  
SIMULATED SIGNAL 3

<u>RESIDUES</u>	<u>POLES</u> (Nep.      GHZ)
$1.0 + i1.0$	$-1.0 + i1.0$
$1.0 - i1.0$	$-1.0 - i1.0$
$0.5 + i0.5$	$-2.0 + i2.0$
$0.5 - i0.5$	$-2.0 - i2.0$
$0.25 + i0.25$	$-3.0 + i3.0$
$0.25 - i0.25$	$-3.0 - i3.0$

The results of varying the number of additional data points from zero (all the data points are from late time region) to ten extra data points (10 extra points are from early time region are added to the points of late time region) are contained in Table IV through XII. These nine

cases correspond to the 3 synthetic signals, each having 3 additive noise levels. The 3 synthetic signals are plotted in Appendix C. In the next section, the accuracy of pole extractions, as indicated in the tables are displayed by way of graphical pole maps. In addition, reconstructed waveform obtained from the parameter extractions are compared graphically to the original waveforms.



TABLE IV

## PARAMETER OPTIMIZATION FOR SIGNAL 1 (NOISE FREE)

## B. RESULTS

TARGET TYPE:TGT-1  
 WAVEFORM TYPE:PCNFTR  
 CONTACT DATE:DEC 15  
 FILE NAME:FILE002  
 NUMB. OF POLE: 2

TABLE OF RESIDUES AND POLES

```
=====
```

PAIR #	RES-REAL	RES-IMAG	POLE-REAL	POLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000

RESULTS OF OPTIMIZATION WITH 0 EXTRA DATA POINTS

```
=====
```

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.999996610	1.00001592	-0.999994705	0.999998971
2	0.999996563	-1.00001375	-0.999994777	-0.999998971

RESULTS OF OPTIMIZATION WITH 2 EXTRA DATA POINTS

```
=====
```

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00000251	0.99999667	-1.00000025	1.00000085
2	1.00000251	-0.99999667	-1.00000026	-1.00000085

RESULTS OF OPTIMIZATION WITH 4 EXTRA DATA POINTS

```
=====
```

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00001308	1.00000329	-1.00001536	0.99999999
2	1.00001311	-1.00000330	-1.00001545	-1.00000002

RESULTS OF OPTIMIZATION WITH 6 EXTRA DATA POINTS

```
=====
```

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.999985213	1.000003040	-0.999979429	0.99998208
2	0.999985210	-1.000003047	-0.999979441	-0.99998213

RESULTS OF OPTIMIZATION WITH 8 EXTRA DATA POINTS

```
=====
```

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00000036	1.000001011	-1.000000472	0.99999818
2	1.00000026	-1.000001041	-1.000000540	-0.99999838

RESULTS OF OPTIMIZATION WITH 10 EXTRA DATA POINTS

```
=====
```

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00000457	0.99999062	-0.99999674	1.00000165
2	1.00000453	-0.99999067	-0.99999675	-1.00000168

TABLE V  
PARAMETER OPTIMIZATION FOR SIGNAL 1  
(SNR=30 dB)

TARGET TYPE:TGT-1  
WAVEFORM TYPE:PCN30TR  
CONTACT DATE:CEC 15  
FILE NAME:FILE003  
NUMB. CF POLE: 2

TABLE CF RESIDUES AND POLES  
=====

PAIR #	RES-REAL	RES-IMAG	POLE-REAL	POLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000

RESULTS CF OPTIMIZATION WITH 0 EXTRA DATA PCINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.01000000	0.92346346	-0.77676493	1.00970076
2	1.03315188	-1.10738236	-1.30247623	0.99197436

RESULTS CF OPTIMIZATION WITH 2 EXTRA DATA PCINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.01070336	1.00360284	-1.00951167	0.99979304
2	1.01070339	-1.00360275	-1.00951163	0.99979306

RESULTS CF OPTIMIZATION WITH 4 EXTRA DATA PCINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.01066217	1.00367655	-1.00953849	0.99977751
2	1.01066632	-1.00367409	-1.00953782	-0.99977735

RESULTS CF OPTIMIZATION WITH 6 EXTRA DATA PCINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.01059740	1.00357123	-1.00930702	0.99978580
2	1.01059679	-1.00357126	-1.00930751	0.99978574

RESULTS CF OPTIMIZATION WITH 8 EXTRA DATA PCINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.01061940	1.00362571	-1.00950587	0.99978686
2	1.01061933	-1.00362636	-1.00950586	-0.99978699

RESULTS CF OPTIMIZATION WITH 10 EXTRA DATA PCINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.01066621	1.00360379	-1.00950576	0.99979175
2	1.01066609	-1.00360399	-1.00950630	-0.99979177

TABLE VI  
PARAMETER OPTIMIZATION FOR SIGNAL 1  
(SNR=15 dB)

TARGET TYPE:TGT-1  
WAVEFORM TYPE:MDN15TR  
CONTACT DATE:CEC 20  
FILE NAME:FILE004  
NUMB. OF POLE: 2

TABLE CF RESIDUES AND POLES  
=====

PAIR #	RES-REAL	RES-IMAG	PCLE-REAL	PCLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000

RESULTS CF OPTIMIZATION WITH 0 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	PCLE-IMAG
1	0.56647982	1.39923892	-0.5789084	0.98886304
2	1.59727710	-0.80336947	-1.57013329	-0.91419374

RESULTS CF OPTIMIZATION WITH 2 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	PCLE-IMAG
1	1.06657099	1.02070489	-1.05306349	0.99869879
2	1.06657923	-1.02071795	-1.05306276	-0.99869878

RESULTS CF OPTIMIZATION WITH 4 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	PCLE-IMAG
1	1.06653386	1.02072970	-1.05304404	0.99868990
2	1.06652818	-1.02073354	-1.05304091	-0.99869088

RESULTS CF OPTIMIZATION WITH 6 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	PCLE-IMAG
1	1.06651499	1.02073547	-1.05295266	0.99873653
2	1.06654674	-1.02072794	-1.05313212	-0.99864419

RESULTS CF OPTIMIZATION WITH 8 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	PCLE-IMAG
1	1.02449720	1.06889916	-0.66485231	1.01775339
2	1.07648258	-1.10030318	-1.63907420	-0.93004124

RESULTS CF OPTIMIZATION WITH 10 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	PCLE-IMAG
1	1.03166928	1.11984550	-1.56675813	0.92761091
2	1.03351816	-1.07048377	-0.68299831	-1.02160947

TABLE VII

PARAMETER OPTIMIZATION FOR SIGNAL 2  
(NOISE FREE)

TARGET TYPE:TGT-2  
WAVEFORM TYPE:HCONFTR  
CONTACT DATE:DEC 15  
FILE NAME:FILE002  
NUMB. CF POLE: 4

## TABLE CF RESIDUES AND POLES

PAIR #	RES-REAL	RES-IMAG	POLE-REAL	POLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000
3	0.50000000	0.50000000	-2.00000000	2.00000000
4	0.50000000	-0.50000000	-2.00000000	-2.00000000

## RESULTS CF OPTIMIZATION WITH 0 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00000054	0.99998637	-1.00000054	1.00000162
2	1.00000019	-0.99998792	-0.99998823	-1.00000180
3	0.499993635	0.500005618	-2.000005518	1.99999365
4	0.499995131	-0.500004431	-2.000024952	-1.999994115

## RESULTS CF OPTIMIZATION WITH 2 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.999906513	0.99549512	-0.99792594	0.99998185
2	0.999906405	-0.99549467	-0.99792606	-0.99998794
3	0.47735342	0.48850313	-1.95118748	1.99896225
4	0.47735838	-0.48850442	-1.95306775	-1.99850918

## RESULTS CF OPTIMIZATION WITH 4 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.999906256	0.99549224	-0.99793418	0.99998541
2	0.999906321	-0.99549228	-0.99793438	-0.99998413
3	0.47737187	0.48848088	-1.95232122	1.998953642
4	0.47736575	-0.48847526	-1.95190026	-1.99893520

## RESULTS CF OPTIMIZATION WITH 6 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.999906743	0.99549467	-0.99793003	0.99998501
2	0.999906717	-0.99549457	-0.99793354	-0.99998468
3	0.47735612	0.48847662	-1.95175495	1.998974576
4	0.47735443	-0.48847686	-1.95248987	-1.998975751

## RESULTS CF OPTIMIZATION WITH 8 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.01514809	0.98882407	-1.12954971	1.01650809
2	1.00949031	-0.98875294	-0.88470066	-0.99067696
3	0.78175371	0.36507609	-2.03189450	2.04744671
4	0.14319323	-0.56814961	-1.55852411	-1.92582259

## RESULTS CF OPTIMIZATION WITH 10 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.02106356	0.98982102	-1.16328021	1.01520699
2	1.02053154	-0.99088746	-0.86815870	-0.99077552
3	0.34656670	0.59967646	-1.95544265	1.95297875
4	0.61555028	-0.57246541	-2.00784742	-2.04312205

TABLE VIII

PARAMETER OPTIMIZATION FOR SIGNAL 2  
(SNR=30 dB)

TARGET TYPE:TGT-2  
WAVEFORM TYPE:FDN30TR  
CONTACT DATE:DEC 15  
FILE NUMB:FILE003  
NUMB. CF POLE: 4

TABLE CF RESIDUES AND POLES

PAIR #	RES-REAL	RES-IMAG	FOLE-REAL	FOLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000
3	0.50000000	0.50000000	-2.00000000	2.00000000
4	0.50000000	-0.50000000	-2.00000000	-2.00000000

## RESULTS CF OPTIMIZATION WITH 0 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	FOLE-REAL	FOLE-IMAG
1	0.995412945	0.99056805	-0.92918755	0.99302604
2	0.99548280	-0.99069937	-1.06493363	-1.00885606
3	0.00000010	0.56023544	-1.96891695	1.90034350
4	0.87406384	-0.32304349	-2.04566871	-2.05396332

## RESULTS CF OPTIMIZATION WITH 2 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	FOLE-REAL	FOLE-IMAG
1	0.99506513	0.99549512	-0.99792594	0.99598185
2	0.99506405	-0.99549467	-0.99792606	-0.99998794
3	0.47735342	0.48850313	-1.95118748	1.99896225
4	0.47735838	-0.48850442	-1.95306779	-1.99850918

## RESULTS CF OPTIMIZATION WITH 4 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	FOLE-REAL	FOLE-IMAG
1	0.99506256	0.99549224	-0.99793418	0.99598541
2	0.99506321	-0.99549228	-0.99791438	-0.99998413
3	0.47737187	0.48848088	-1.95232122	1.99855642
4	0.47736977	-0.48847526	-1.95190026	-1.99893520

## RESULTS CF OPTIMIZATION WITH 6 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	FOLE-REAL	FOLE-IMAG
1	0.99506743	0.99549467	-0.99793003	0.99598501
2	0.99506717	-0.99549457	-0.99792354	-0.99998468
3	0.47739612	0.48847662	-1.95179495	1.99874576
4	0.47739443	-0.48847686	-1.95248987	-1.99875751

## RESULTS CF OPTIMIZATION WITH 8 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	FOLE-REAL	FOLE-IMAG
1	1.01514809	0.98882407	-1.12954971	1.01650809
2	1.00549031	-0.98875294	-0.88470066	-0.99067696
3	0.78175371	0.36507609	-2.03185450	2.04744671
4	0.14319333	-0.56814961	-1.95892411	-1.92582259

## RESULTS CF OPTIMIZATION WITH 10 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	FOLE-REAL	FOLE-IMAG
1	1.02706396	0.98982102	-1.16328021	1.01620699
2	1.02053154	-0.98988746	-0.86815870	-0.99077552
3	0.34656670	0.59907646	-1.95544265	1.95257875
4	0.61555028	-0.37246541	-2.00784742	-2.04312205

TABLE IX

PARAMETER OPTIMIZATION FOR SIGNAL 2  
(SNR=15 dB)

TARGET TYPE: TGT-2  
WAVEFORM TYPE: PDN15TR  
CONTACT DATE: DEC 15  
FILE NAME: FILE004  
NUMB. CF POLE: 4

TABLE CF RESIDUES AND POLES  
\*\*\*\*\*

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000
3	0.50000000	0.50000000	-2.00000000	2.00000000
4	0.50000000	-0.50000000	-2.00000000	-2.00000000

## RESULTS CF OPTIMIZATION WITH 0 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.96091205	0.96731225	-0.97658042	0.99822948
2	0.96092603	-0.96731915	-0.97544458	-0.99811586
3	0.52207777	0.22152280	-1.54313287	2.10614539
4	0.00000010	-0.42428522	-1.38794994	-1.83372419

## RESULTS CF OPTIMIZATION WITH 2 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.96511311	0.96627888	-0.99390301	1.00027364
2	0.96526467	-0.96632064	-0.95966500	-0.99679353
3	0.00000010	0.49329107	-1.46905167	1.85021464
4	0.55450458	-0.13648901	-1.66572130	-2.12454838

## RESULTS CF OPTIMIZATION WITH 4 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.96128516	0.96679315	-0.98935769	0.99965070
2	0.96144733	-0.96682559	-0.96226170	-0.99687448
3	0.00000010	0.54101355	-1.50069226	1.85232329
4	0.50251363	-0.09527370	-1.60980060	-2.13416731

## RESULTS CF OPTIMIZATION WITH 6 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.06254479	0.93763540	-1.25949424	1.04372728
2	1.01484084	-0.94095523	-0.77277970	-0.98546978
3	0.62674427	0.16116490	-1.75036751	2.11201876
4	0.00000010	-0.51970056	-1.59036824	-1.84519866

## RESULTS CF OPTIMIZATION WITH 8 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.96304511	0.96782052	-0.98445408	0.99905219
2	0.96312358	-0.96782270	-0.96540893	-0.99752145
3	0.00000010	0.35719908	-1.36627593	1.83147922
4	0.54632361	-0.25136131	-1.56644065	-2.10011865

## RESULTS CF OPTIMIZATION WITH 10 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00971067	0.96985420	-1.20987398	1.02332284
2	1.00285344	-0.97024550	-0.81824047	-0.98822709
3	0.57607620	0.19510021	-1.66621998	2.10722391
4	0.00000010	-0.50028280	-1.53834141	-1.84201571

TABLE X  
PARAMETER OPTIMIZATION FOR SIGNAL 3  
(NOISE FREE)

TARGET TYPE:TGT-3  
WAVEFORM TYPE:FCNFTF  
CONTACT DATE:DEC 15  
FILE NUMB:FILE004  
NUMB. CF FOLE: 6

TABLE CF RESIDUES AND POLES  
=====

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	FOLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000
3	0.50000000	0.50000000	-2.00000000	2.00000000
4	0.50000000	-0.50000000	-2.00000000	-2.00000000
5	0.25000000	0.25000000	-3.00000000	3.00000000
6	0.25000000	-0.25000000	-3.00000000	-3.00000000

RESULTS CF OPTIMIZATION WITH 0 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	FOLE-IMAG
1	1.00000029	0.99999951	-1.00000013	1.00000000
2	0.99999965	-1.00000047	-0.99999985	-0.99999999
3	0.50000021	0.49999977	-1.99999933	1.99999965
4	0.49999957	-0.50000051	-2.00000029	-2.00000029
5	0.25000049	0.25000087	-2.99876241	2.99999966
6	0.24999968	-0.24999958	-3.00125324	-2.99999961

RESULTS CF OPTIMIZATION WITH 2 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	FOLE-IMAG
1	1.00000033	1.00000006	-0.99999964	0.99999972
2	0.99999970	-0.99999990	-1.00000035	-1.00000028
3	0.49999957	0.49999976	-2.00000082	1.99999976
4	0.50000019	-0.49999970	-1.99999987	-2.00000017
5	0.24999932	0.25000063	-2.99929864	2.99999940
6	0.25000078	-0.24999948	-3.00067868	-3.00000033

RESULTS CF OPTIMIZATION WITH 4 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	PCLE-REAL	FOLE-IMAG
1	1.00000031	1.00000004	-0.99999929	0.99999999
2	1.00000008	-0.99999999	-1.00000084	-1.00000003
3	0.50000029	0.49999987	-2.00000158	2.00000057
4	0.50000073	-0.49999913	-1.99999974	-1.99999986
5	0.24999713	0.25000137	-3.00006822	3.00000834
6	0.25000306	-0.24999453	-2.99952441	-2.99999365

RESULTS CF OPTIMIZATION WITH 6 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	C.55555967	1.00000006	-0.99999978	0.99999979
2	0.95555949	-1.00000005	-1.00000003	-1.00000016
3	C.50000350	0.49995519	-2.00000411	-2.00000118
4	C.50000357	-0.49995515	-2.00000565	-2.00000116
5	0.25002351	0.25003725	-3.01254931	-2.99994026
6	0.24555017	-0.25002880	-2.98710887	-2.99987758

RESULTS GF OPTIMIZATION WITH 8 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00000000	0.99999980	-0.99999966	1.00000029
2	1.00000001	-1.00000010	-1.00000031	-0.99999975
3	0.50000063	0.49995686	-2.00000881	-1.99969134
4	0.45555753	-0.50003918	-1.99998120	-2.00030891
5	0.25006787	0.25234001	-3.00656319	-3.00052848
6	0.24513768	-0.24765392	-2.99334543	-2.99547896

RESULTS CF OPTIMIZATION WITH 10 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	1.00000004	0.99999995	-1.00000147	1.00000006
2	0.95555954	-1.00000008	-0.999999854	-0.99999994
3	0.50000006	0.50000023	-2.00001924	-1.99999846
4	C.50000019	-0.50000011	-1.99998131	-2.00000154
5	0.25000013	0.25000022	-2.99992168	-2.99997583
6	C.25000024	-0.25000077	-3.00008161	-3.00002582



TABLE XI  
PARAMETER OPTIMIZATION FOR SIGNAL 3  
(SNR=30 dB)

TARGET TYPE:TGT-3  
WAVEFORM TYPE:HON30TR  
CONTACT DATE:DEC 15  
FILE NJMB:FILE004  
NUMB. OF POLE: 6

TABLE OF RESIDUES AND POLES  
=====

PAIR #	RES-REAL	RES-IMAG	POLE-REAL	POLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000
3	0.50000000	0.50000000	-2.00000000	2.00000000
4	0.50000000	-0.50000000	-2.00000000	-2.00000000
5	0.25000000	0.25000000	-3.00000000	3.00000000
6	0.25000000	-0.25000000	-3.00000000	-3.00000000

RESULTS OF OPTIMIZATION WITH 0 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.99145389	0.98947089	-0.99318094	1.00001443
2	0.99145320	-0.98947086	-0.99310558	-1.00001237
3	0.42807658	0.52733218	-1.99204259	1.97341708
4	0.42846454	-0.52679082	-1.92072086	-1.99797545
5	0.11656813	0.23647261	-2.27124794	2.83611689
6	0.12939770	-0.21591933	-2.24119798	-3.06874116

RESULTS OF OPTIMIZATION WITH 2 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.99147340	0.98938441	-0.99323692	1.00002118
2	0.99147541	-0.98938831	-0.99299518	-1.00001483
3	0.42927584	0.52783363	-1.96123606	1.86208680
4	0.42938721	-0.52783004	-1.96042724	-1.98830969
5	0.13113198	0.20433430	-2.22870752	3.07350223
6	0.10954559	-0.24676563	-2.28661642	-2.83356831

RESULTS OF OPTIMIZATION WITH 4 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.99149793	0.98938042	-0.99300311	1.00001643
2	0.99149653	-0.98937734	-0.99323733	-1.00002228
3	0.42898254	0.52744729	-1.95708423	1.98692809
4	0.42897578	-0.52746013	-1.96340662	-1.98537735
5	0.13728153	0.20601283	-2.24720729	3.07453032
6	0.10518882	-0.24183713	-2.27543055	-2.83274078

# RESULTS OF OPTIMIZATION WITH 6 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.99181508	0.98944282	-0.99314260	1.00003060
2	0.99181556	-0.98944354	-0.99332473	-1.00003549
3	0.43071414	0.52480605	-1.97634267	1.98151201
4	0.43071211	-0.52479742	-1.93934530	-1.99173878
5	0.15055056	0.25270674	-2.28536097	2.85503019
6	0.10533241	-0.20048107	-2.19638655	-3.07720611

# RESULTS OF OPTIMIZATION WITH 8 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.98171120	0.98981745	-0.99074872	0.99947232
2	0.98171187	-0.98981744	-0.99060276	-0.99945877
3	0.30805732	0.49840155	-1.88871352	1.87285997
4	0.31532825	-0.51226642	-1.56132982	-2.02127811
5	0.11572596	0.13443903	-1.99741621	3.12706630
6	0.07739011	-0.19217344	-1.89148981	-2.85558132

# RESULTS OF OPTIMIZATION WITH 10 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.99337417	0.99015792	-0.99418591	1.00008890
2	0.99337150	-0.99015803	-0.99369290	-1.00007652
3	0.44239542	0.52004030	-1.95770753	1.99113003
4	0.44239753	-0.52004768	-1.96547995	-1.98746271
5	0.15478007	0.23652063	-2.41828246	2.87099551
6	0.15377770	-0.23805063	-2.48497797	-3.06515871

TABLE XII

PARAMETER OPTIMIZATION FOR SIGNAL 3  
(SNR=15 dB)

TARGET TYPE:TGT-3  
WAVEFORM TYPE:FCN15TR  
CONTACT DATE:CEC 15  
FILE NUME:FILE004  
NUMB. CF POLE: 6

TABLE CF RESIDUES AND POLES  
=====

PAIR #	RES-REAL	RES-IMAG	POLE-REAL	POLE-IMAG
1	1.00000000	1.00000000	-1.00000000	1.00000000
2	1.00000000	-1.00000000	-1.00000000	-1.00000000
3	0.50000000	0.50000000	-2.00000000	2.00000000
4	0.50000000	-0.50000000	-2.00000000	-2.00000000
5	0.25000000	0.25000000	-3.00000000	3.00000000
6	0.25000000	-0.25000000	-3.00000000	-3.00000000

RESULTS CF OPTIMIZATION WITH 0 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.96625765	0.94693282	-0.96776691	1.00067712
2	0.96625659	0.94693466	-0.96776960	-1.00067721
3	0.25178800	0.55401616	-1.81344345	1.95442546
4	0.25178439	0.55401729	-1.81338128	-1.95442985
5	0.00000010	0.30602226	-2.40607412	2.86369297
6	0.00000010	-0.30602324	-2.40740413	-2.86372990

RESULTS CF OPTIMIZATION WITH 2 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.97003027	0.94583414	-0.96792409	1.00081726
2	0.97002941	-0.94583770	-0.96792108	-1.00081754
3	0.25168247	0.53580191	-1.78711241	1.95425944
4	0.25167543	-0.53579888	-1.78712746	-1.95423795
5	0.00000010	0.26710278	-2.24090416	2.86059552
6	0.00000010	-0.26681661	-2.24551510	-2.87417393

RESULTS CF OPTIMIZATION WITH 4 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	0.97144662	0.94762010	-0.96904247	1.00080514
2	0.97144593	-0.94762088	-0.96905146	-1.00080547
3	0.25597577	0.54275341	-1.80291116	1.95565280
4	0.25597714	-0.54275353	-1.80292514	-1.95564222
5	0.00000010	0.27664033	-2.30082557	2.86676095
6	0.00000010	-0.27744624	-2.27353152	-2.86430662

# RESULTS OF OPTIMIZATION WITH 6 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	C.97C74646	0.94593786	-0.96820496	1.00084896
2	0.97C74740	-0.94593893	-0.96820018	-1.00084921
3	0.25317420	0.53401680	-1.78619717	1.95473602
4	0.25317461	-0.53401801	-1.78618621	-1.95473121
5	0.00000010	0.26390985	-2.23469098	2.86848662
6	C.00000010	-0.26397500	-2.23254981	-2.86625171

# RESULTS OF OPTIMIZATION WITH 8 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	C.97233004	0.94707234	-0.96927693	1.00087271
2	0.97233259	-0.94707302	-0.96903353	-1.00086402
3	0.24416111	0.53457339	-1.78489285	1.95562845
4	C.24415737	-0.53465427	-1.79548721	-1.94953438
5	0.00000010	0.20134605	-1.70725522	2.99741937
6	C.00000010	-0.21428806	-1.61287861	-2.76554177

# RESULTS OF OPTIMIZATION WITH 10 EXTRA DATA POINTS

PAIR #	RES.-REAL	RES.-IMAG	POLE-REAL	POLE-IMAG
1	C.97265829	0.94587240	-0.97006813	1.00100830
2	0.97266290	-0.94587709	-0.96753425	-1.00089816
3	0.24466698	0.52883260	-1.77855047	1.95554555
4	C.24466604	-0.52886614	-1.78467362	-1.95508659
5	C.00000010	0.25592515	-1.69222053	2.78203752
6	C.00000010	-0.15339728	-1.60711251	-3.01800673

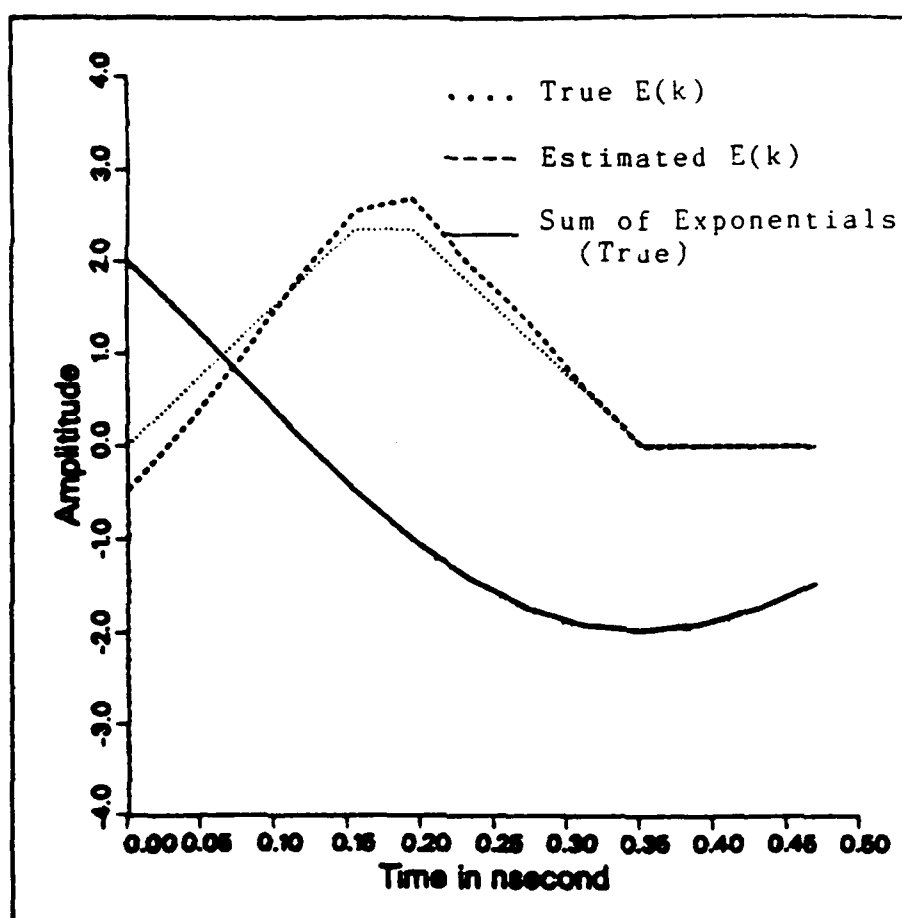


Figure 5.1. Estimated  $E(k)$  for Signal 1 of 15 dB SNR. (32 data points from late time region).

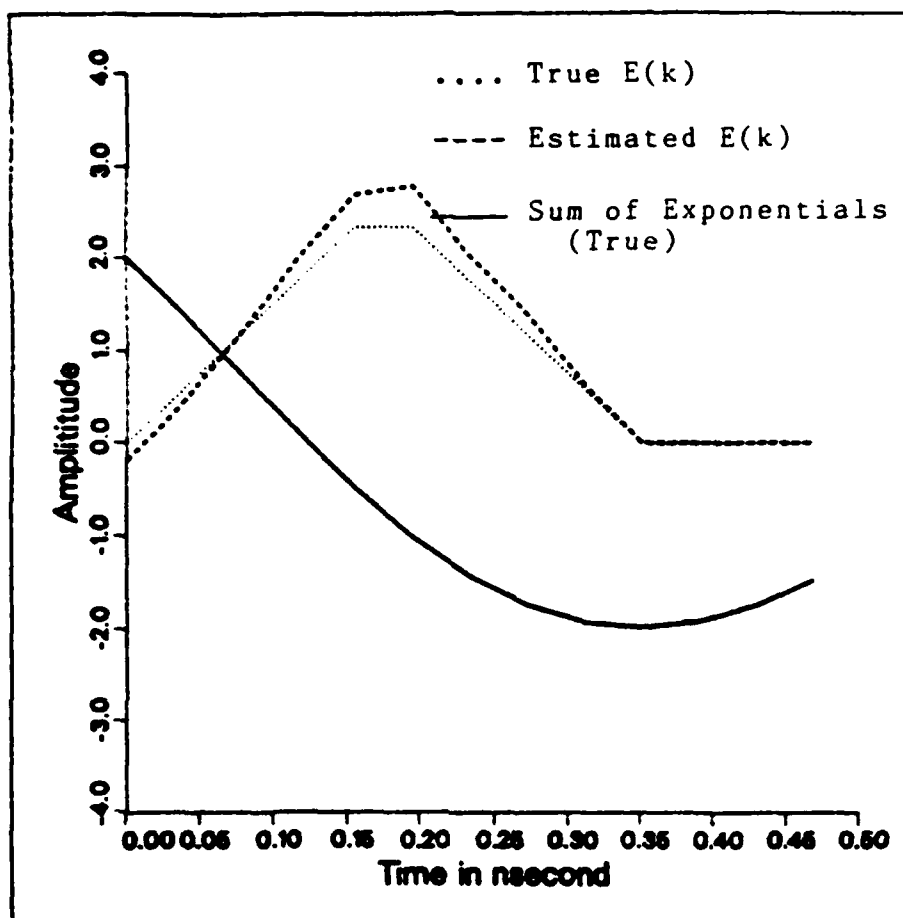


Figure 5.2. Estimated  $E(k)$  for Signal 1 of 15 dB SNR. (48 data points from late time region).

# SIGNAL 1 ( NOISE FREE )

□ : RESIDUE (IRUF)  
 x : POLE (IRUF)

Δ : 1ST SIFP (WITH EXTRA 0 POINTS)  
 • : 2ND SIFP (WITH EXTRA 2 POINTS)  
 • : 3RD SIFP (WITH EXTRA 4 POINTS)

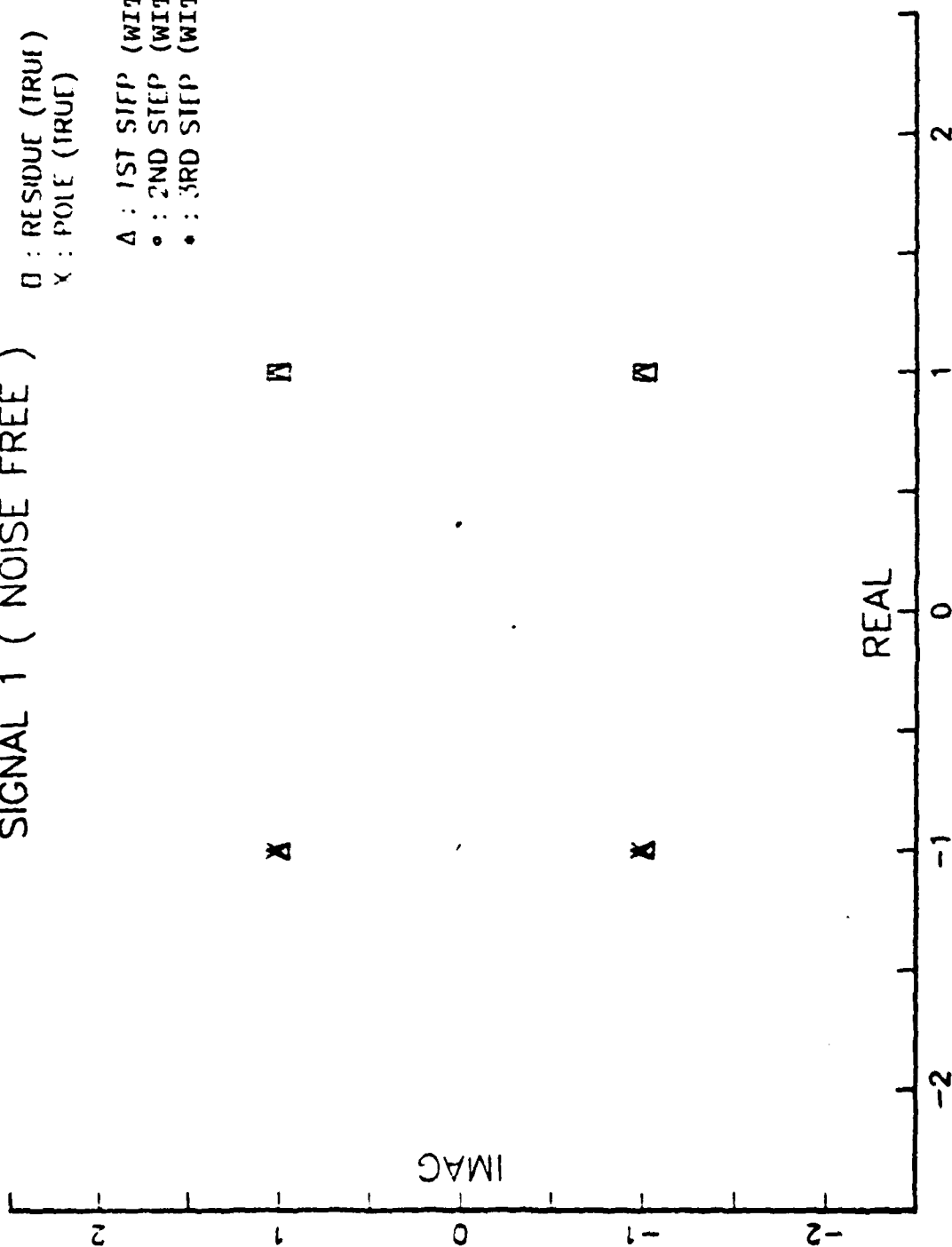


Figure 5.3. Pole and Residue Plot for Signal 1 of Noise Free.

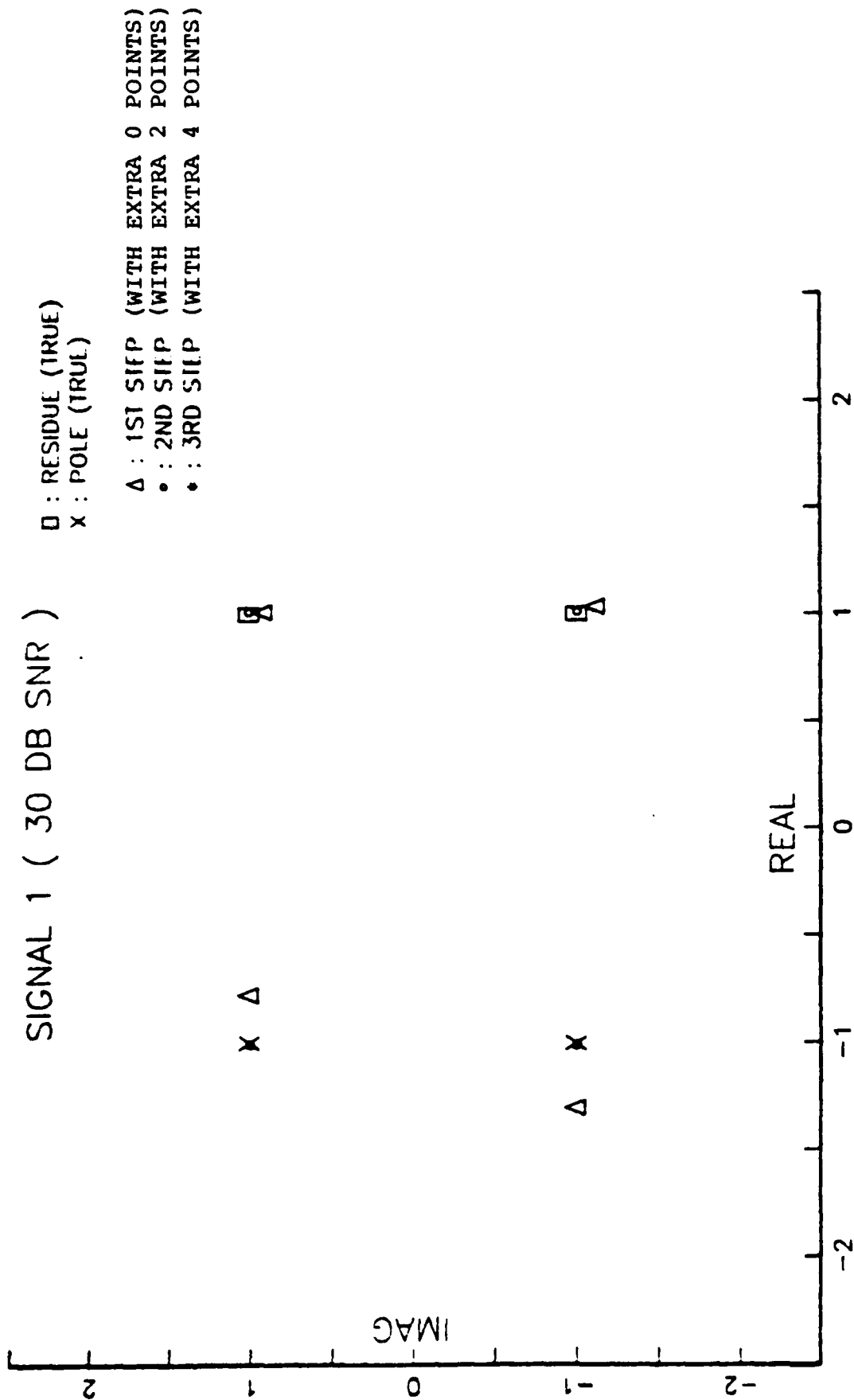


Figure 5.4. Pole and Residue Plot for Signal 1 of 30 dB SNR.



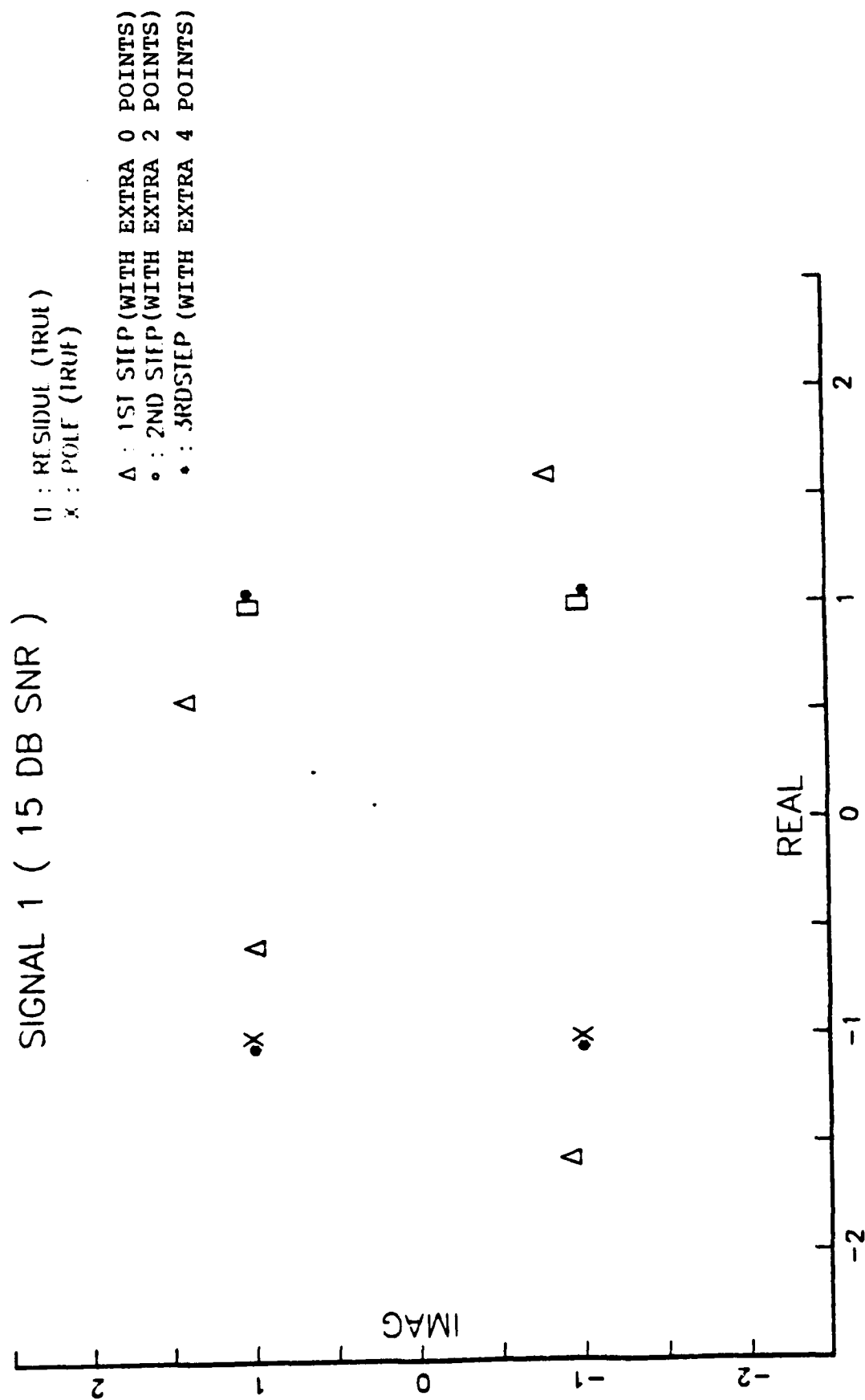


Figure 5.5. Pole and Residue Plot for Signal 1 of 15 dB SNR.

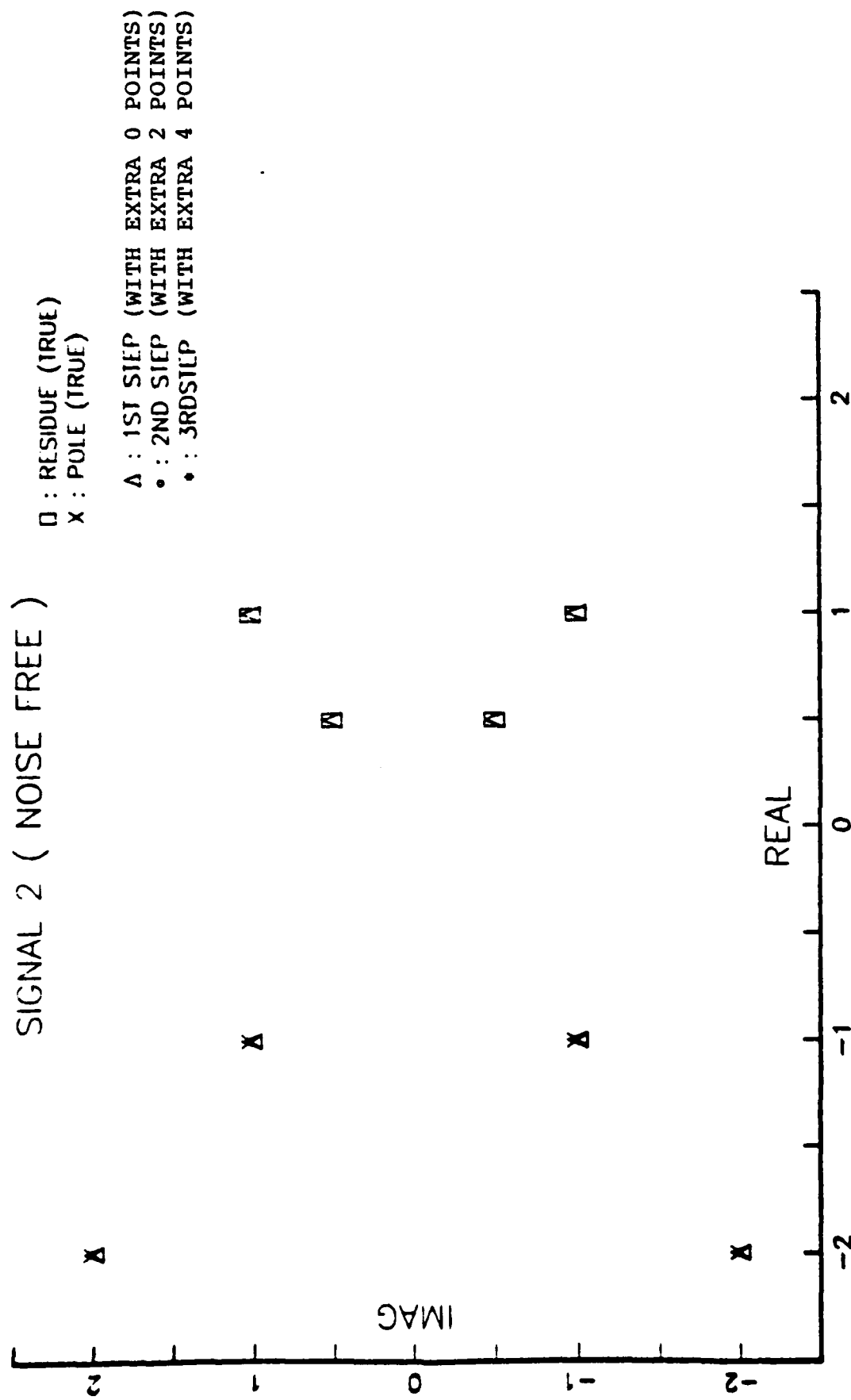


Figure 5.6. Pole and Residue Plot for Signal 2 of Noise Free.

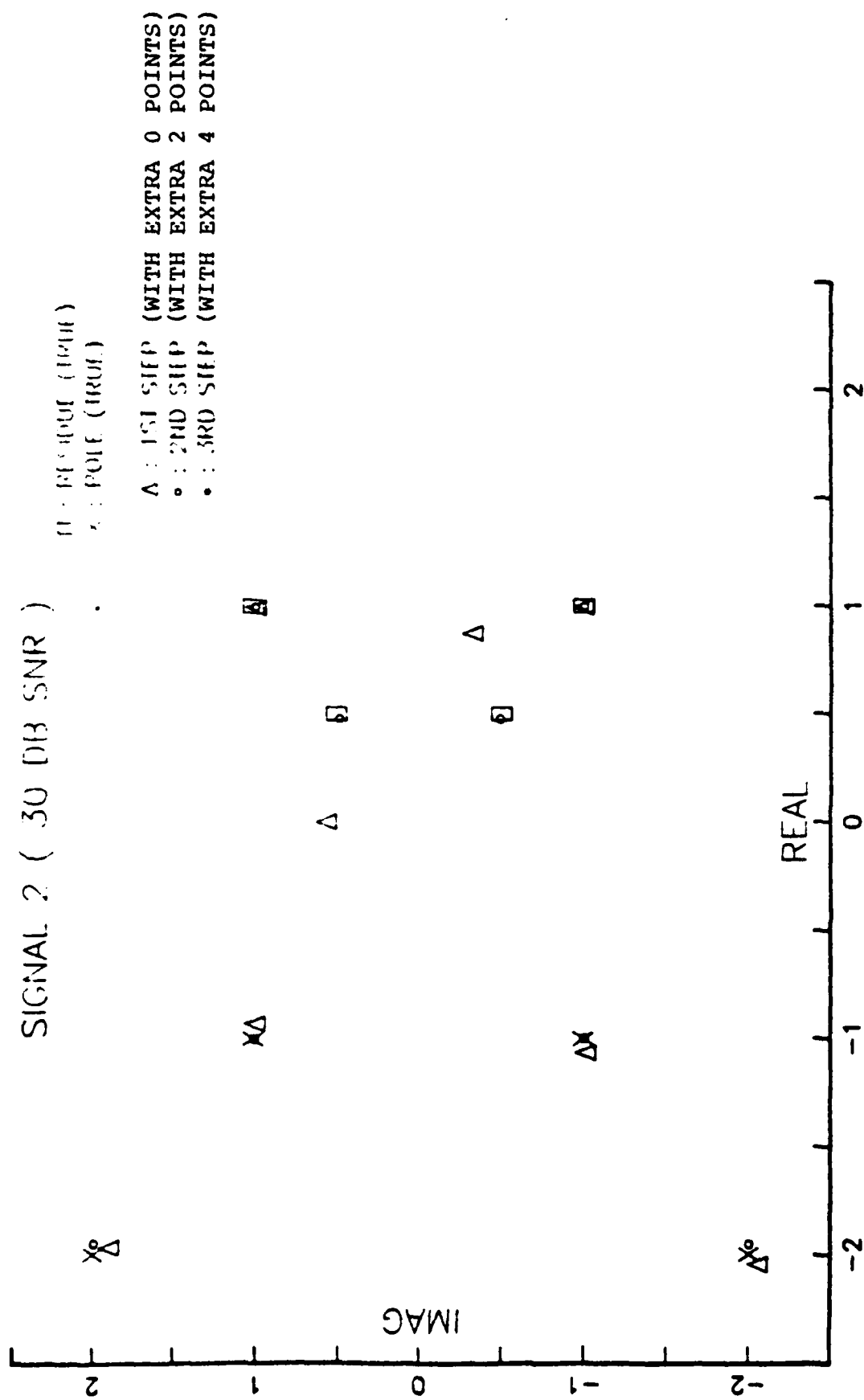


Figure 5.7. Pole and Residue Plot for Signal 2 of 30 dB SNR.

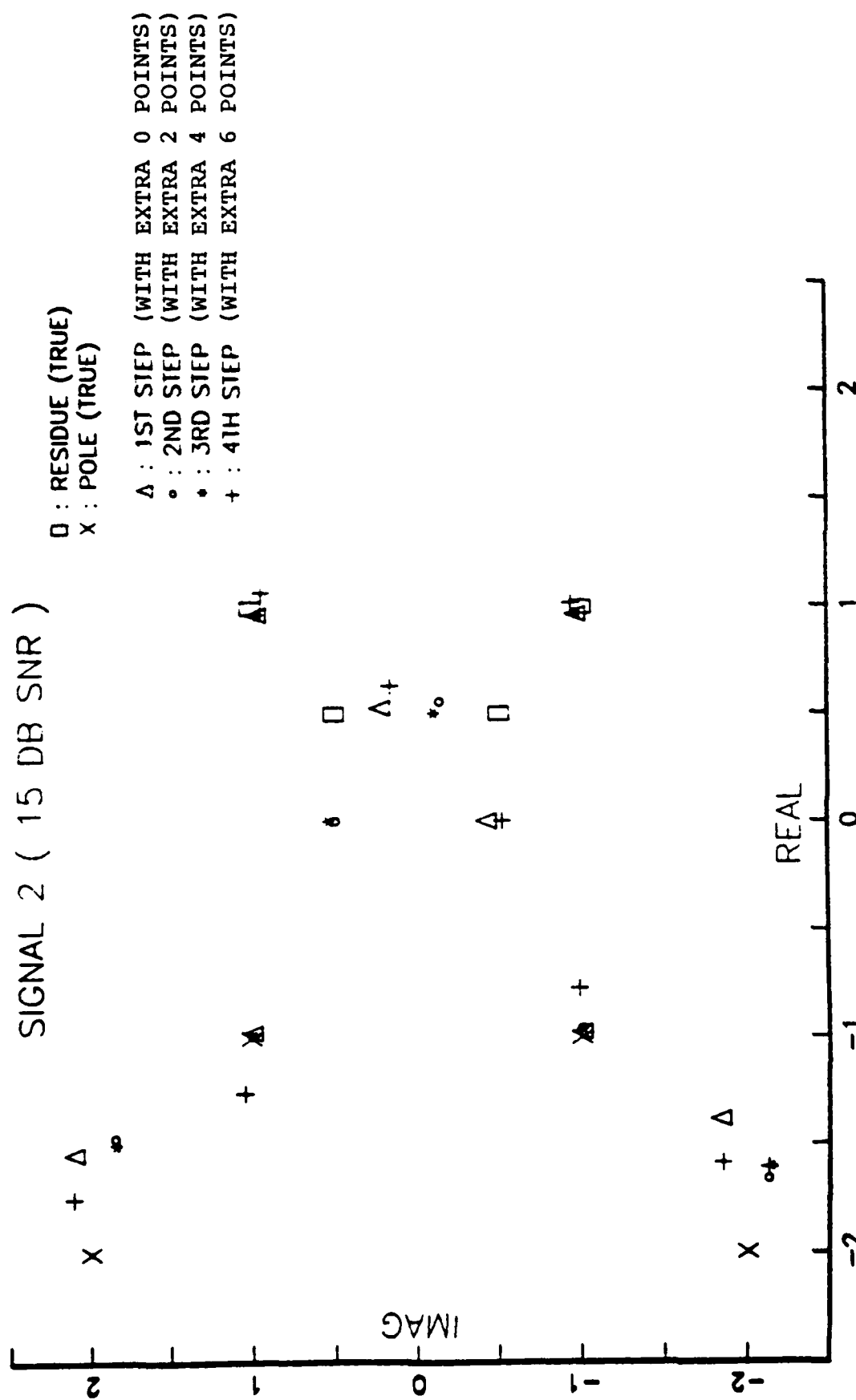


Figure 5.8. Pole and Residue Plot for Signal 2 of 15 dB SNR.

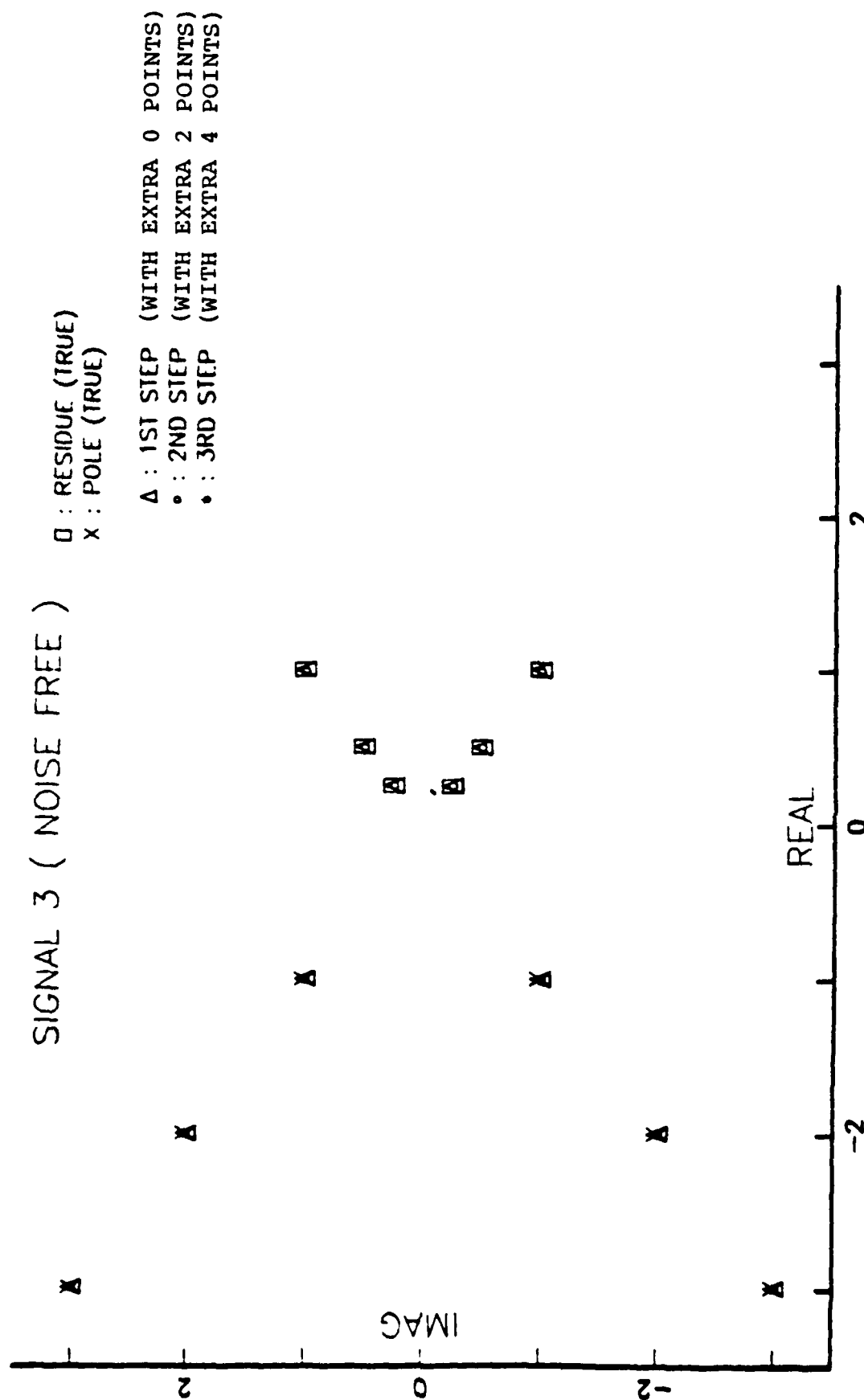


Figure 5.9. Pole and Residue Plot for Signal 3 of Noise Free.

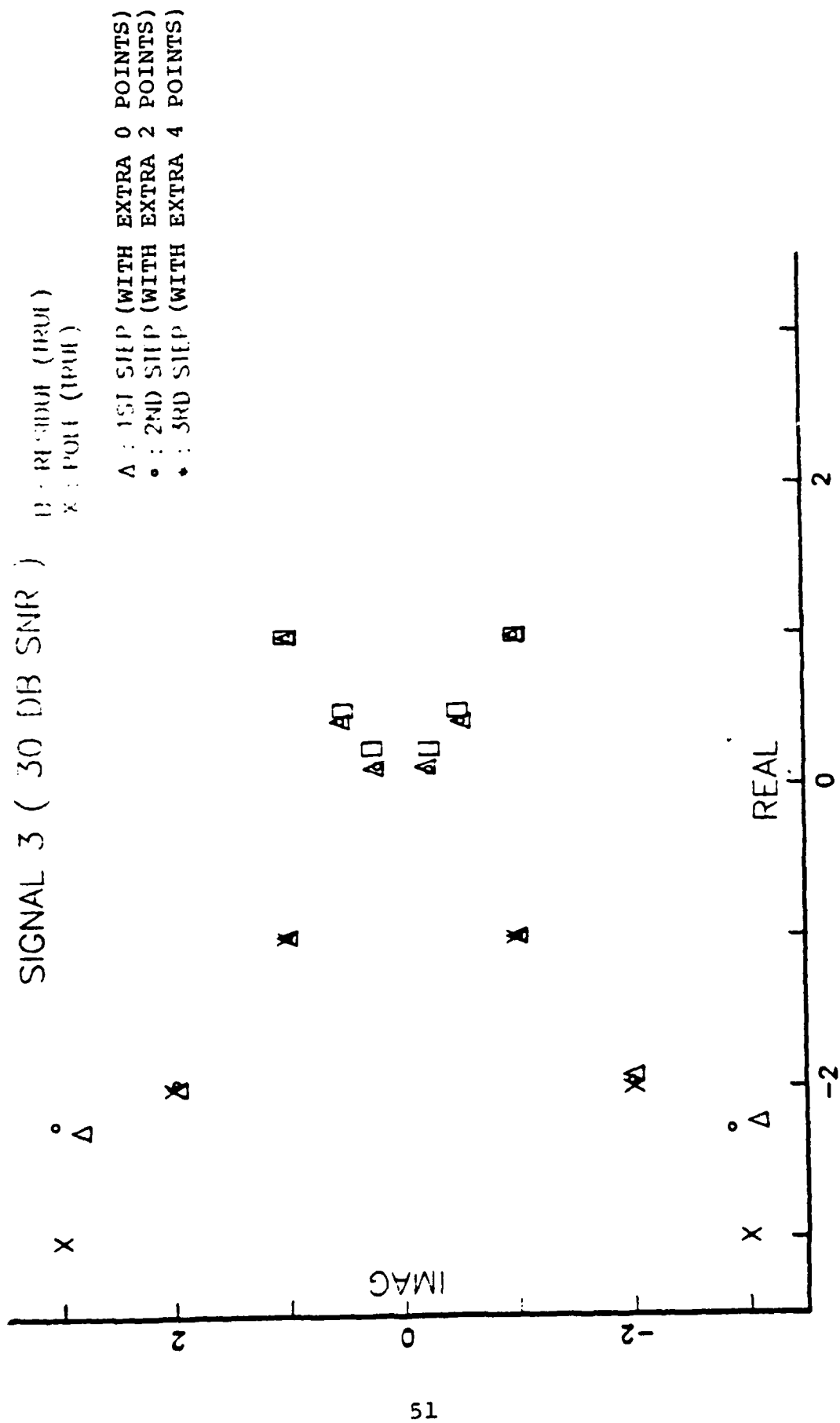


Figure 5.10. Pole and Residue Plot for Signal 3 of 30 dB SNR.

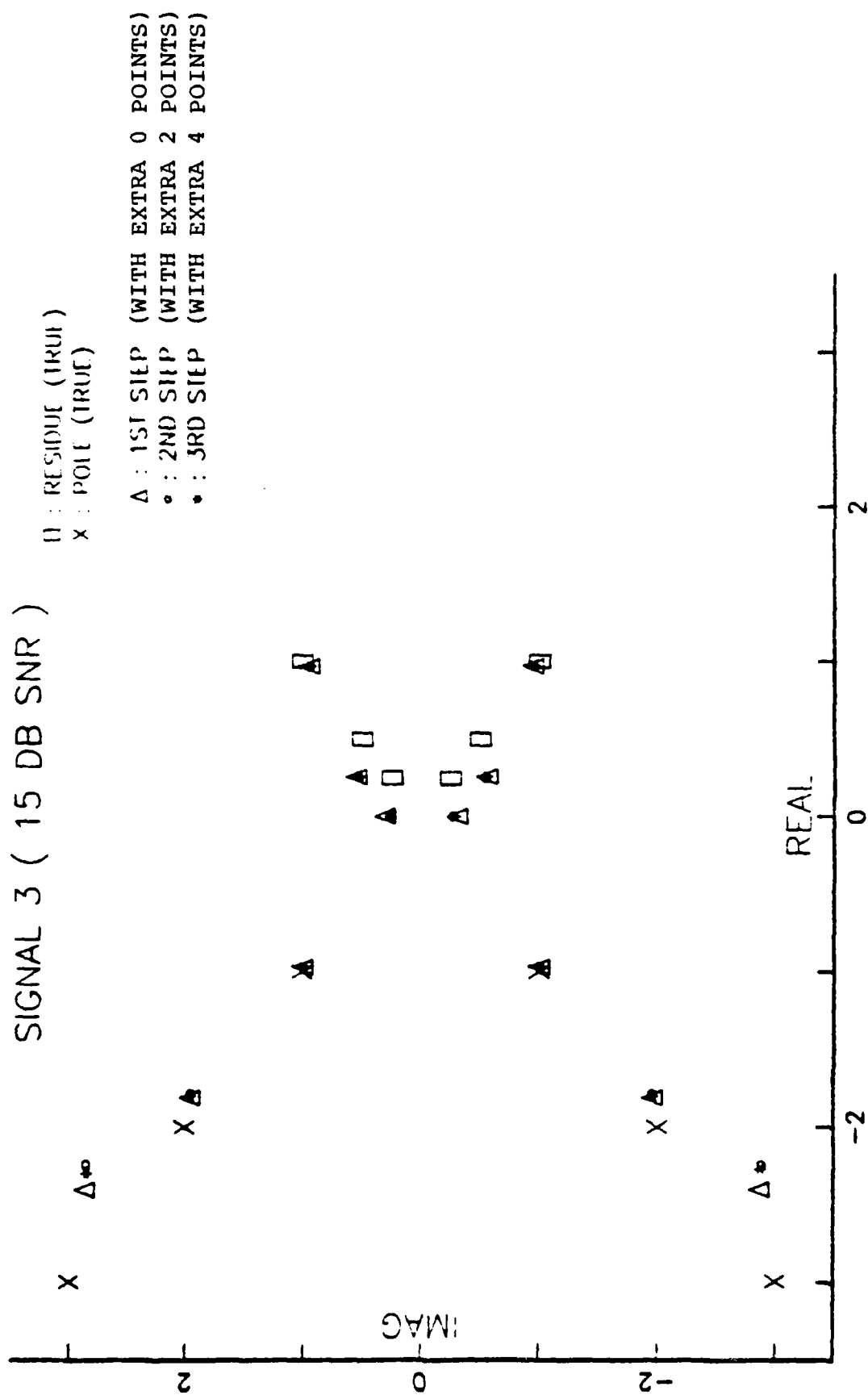


Figure 5.11. Pole and Residue Plot for Signal 3 of 15 dB SNR.

### C. PERFORMANCE EVALUATION

Unlike the traditional methods, this method revealed itself as one that can be applicable to a general scattering problem, including the early time data. A potential superiority of this method over the traditional methods is found in its capability of handling the early time signal that has relatively large energy content and less sensitivity to the fixed noise level.

Regarding the capability of handling the early time signal, the performance of this method seems to be very high compared with the traditional methods which do not model that signal generically. But, two points need to be considered when we ensure this high degree of performance. One important point is that we be able to estimate properly the number of poles to optimally ask for. This will depend upon the SNR of the data, increasing generally with increasing SNR. The actual physical scattering data has an infinite number of poles but, because the energy content of natural modes tends to drop off rapidly beyond the bandwidth of the excitation signal the higher order poles are ignored, blending with the noise present. Another point is that the initial data window has to contain only the late time signal data.

As the results of the tables in the previous pages indicate, converging characteristics of the value of parameters is not blocked by a high level of noise pollution. It has been observed that the computed value of poles are likely to



converge closely to the true values that are listed in Tables I through III either by choosing the number of poles as small or by increasing the size of the data window. Even though it is hard to prove this optimality of this method (due to the non-linearity of the scattering transient response signal model), handling of the early time signal seems to be cast into a simpler problem space and that optimality may be explained by observing the parameters at every processing step. Namely, the parameter estimation of this method is less influenced by the unreliable points than the more accurate ones. Figure 5.1 and 5.2 and the results in the previous section explain the reason why the above assertion is valid. We see that the estimated value of parameters through optimization is not going to worse as we include the early time data points (these data points can be regarded as the unreliable data when we extrapolate the sum of exponentials of the late time region into those of the early time region) into the data window what we see. But, as we are adding more data points of the late time region, improved values of parameters are obtained through processing, as in the results and Fig. 5.2. Although this is true, we still see that the plot of  $E(k)$  in Fig. 5.2 does not provide sufficient data to confirm that an improvement of accuracy depends only on the number of late time data points, because those data points have a lower level of SNR locally. Now, let us get back to Tables IV, VII, and X. For the signal inputs whose SNRs are assumed to be

infinite (noise free), we have a set of parameters whose values are not converging to the true values as we add an increased number of unknowns. These results ensure us that the increased computer round-off errors obtained by more data processing (more parameters to extract) will produce divergence. Even initially with low SNR, the increased signal energy in the additive early-time data may improve the results until, by adding enough extra data points and parameters, round-off error will eventually catch up with the most optimized one and beyond a specific point the results will begin to diverge. So that, in a general sense, we can say that the improvement in accuracy may be obtained either by the number of data points or by making use of the data points of high SNRs. If we consider a signal having high damping coefficients we can not use the signal data what are likely to be hidden by noise. The technique used here in processing the data proceeds by sliding the first data point along the time-axis towards the origin until the data window expands its range up to time-origin by adding the unknown parameters  $E(k)$ 's which is the same as the number of data points in the early time region.

Figures 5.3 through 5.11 shows how rapidly the parameters we want to derive converge to the true values, within a convergence bounds. Here, all the plots were reconstructed from the results.

## VI. SUMMARY

A modified least-squares minimization method has been developed and tested against synthetically generated signal data using a non-linear parameter optimization algorithm. The effect of varying the number of data points either in the region of early time or in the late time under various typical noise environments has been studied, defining the criteria for using this algorithm for the extraction of poles and residues under relatively heavy background noise, as well as for the time varying residue signals modeled by Morgan [Ref. 4].

In an attempt to use this method for signals with high damping coefficients, 3 synthetically generated signals were used as the inputs (Appendix C). Extraction of poles from the direct synthetic signal waveform was done through non-linear numerical evaluations, not by the Prony-based evaluations which were used in the traditional method. The parameter estimating algorithm for this non-linear signal model had worked successfully, providing users with optimized parameters that were converging to the true values, within specified convergence bounds. It was found that although we have the early time signal data having very high SNR, those data can not contribute to improving accuracy by simply increasing the number of extra data points and extra unknown parameters.

In order to get more accurate values of poles, we have to have an increased base of late time signal data, which have relatively low SNR.

It has been shown that this method is "robust" even under heavy noise conditions. But three basic requirements have to be met for using this method as a general methodology; the optimal number of requested poles has to be known in advance to processing, reasonable initial estimation of parameters has to be made, and the transition time from early to late time signal models has to be known a priori.

```

*** DGEN - MAIN PROGRAM : GENERATES SYNTHETIC TRANSIENT RESPONSE ***
*** FOR TESIS RESERACH DATA OF 512 POINTS ***
*** DEC 20, 1983 (#550) CHONG, CHOONG YEUN ***
***
IMPLICIT REAL*8 (A-T,C-Z)
DIMENSION AGDF(5001)
DIMENSION RI(64),R2(64),P1(64),P2(64)
DIMENSION XO(512),XNO(512)
DATA IV,Y,V,I,Z,N /
DATA
DATA
DATA
D2P31M/2147483647.D0/
D2P31/2147483648.D0/
=====
CLEAR SCREEN
CALL FRTCHMS('CLRSCRN ')
=====
DATA GENERATION MODE SELECTION
WRITE(6,61)
61 FORMAT(1X,/,10X,*** SYNTHETIC SIGNAL DATA GENERATION *** ,
/,10X,INTERACTIVE PROGRAM EXECUTION BEGINS. ,
/,10X,/,10X,*** THIS PROGRAM GENERATES 512 POINTS OF DIGITAL
/,10X,*** SIGNAL (TRADITIONAL CR NEW MODEL) SYNTHETICALLY ,
/,10X,*** EITHER IN NOISE-FREE CR NOISE POLLUTING MODE. ,
/,10X,*** USER IS ASKED TO INPUT THE DATA GENERATING PARAMETERS
/,10X,INTERACTIVELY. ,1X,TYPE <G> TO GC IF YOU READY TO INPUT.)
* READ(5,1) IANS
51 FORMAT(11)
C INITIALIZE I.C.N. MAXIMUM 64 POLES
DO 10 I=1,64
RI(I)=0
R2(I)=0
P1(I)=0
P2(I)=0
10
C GET THE DATA IDENTIFIERS
CALL CALL HEADER(NT1,NT2,NW1,NW2,ND1,ND2,NF1,NF2)
C GET THE DATA PARAMETERS
CALL CALL PAF(NT1,T2,S1)
C GET THE DATA PARAMETERS-S-POLES/RESIDUES INTERACTIVELY
WRITE(6,311)

```

```

311 FORMAT(IX,'DO YOU WANT TO GET TRUE POLE/ZERCS FROM THE PRE-DEFINED
* DATA FILE? -<Y/N>.',
READ(5,1) IANS
IF(IANS.NE.IV) GO TO 312
CALL DATA(N1,R1,R2,P1,P2)
GO TO 313
C
312 CALL RPIN(N1,R1,R2,P1,P2)
C
C VERIFICATION POINT - DISPLAY OF POLE AND RESIDUE TABLE
313 WRITE(6,62)
62 FORMAT(IX,'DO YOU WANT TO HAVE THE RES/POLES IN A TABLE FORM? - <Y
*/N>.',
READ(5,51) IANS
IF(IANS.NE.IV) GO TO 990
CALL FRICMS('CLRSCRN.')
CALL DISPI(NT1,NT2,NW1,NW2,ND1,ND2,NF1,NF2,N1,R1,R2,P1,P2)
99C CONTINUE
C
C NOISE-FREE SYNTHETIC DATA GENERATOR
WRITE(6,63)
63 FORMAT(IX,'DO YOU WANT TO GENERATE A NCISE-FREE SIGNAL? - <Y/N>.',
READ(5,51) IANS
IF(IANS.NE.IV) GO TO 991
CALL GNFD(N1,R1,R2,P1,P2,T2,S1,M9,X0)
991 CONTINUE
C
CALL HEADER(NT1,NT2,NW1,NW2,ND1,ND2,NF1,NF2)
C
C NOISE-FREE DATA SIGNAL DISPLAY
WRITE(6,58)
58 FORMAT(IX,'DO YOU WANT TO SEE THE NCISE FREE SIGNAL IN A TABLE FOR
*M? - <Y/N>.',
READ(5,51) IANS
IF(IANS.NE.IV) GO TO 992
N2=0
CALL DISP2(NT1,NT2,NW1,NW2,ND1,ND2,NF1,NF2,N2,T2,S1,X0)
992 CONTINUE
IF LAG=0
GO TO 5111
C
C NOISE POLLUTED SYNTHETIC DATA GENERATOR
6111 IF LAG=1
WRITE(6,59)
59 FORMAT(IX,'DO YOU WANT TO GENERATE A NCISE-POLLUTED SIGNAL DATA? -
* <Y/N>.',
READ(5,51) IANS
IF(IANS.EQ.IZ) GO TO 9999

```

```

C GENERATE THE GAUSSIAN DISTRIBUTION
CALL GALSS(AGDF,IWA,IGA)
GO TO 444

C OPTIONS FOR POLLUTING MODE
444 WRITE(6,64)
64 FORMAT(IX,'CHOOSE ONE OF THE THREE MODES OF NOISE POLLUTION',
*//,
IX,'1: IN TERMS OF SNR(AVERAGE) IN DECIBEL',
*//,
IX,'2: IN TERMS OF SNR(PEAK) IN DECIBEL',//)
READ(5,*) IR

C ADJUST NOISE LEVEL IN QUICK
CALL TRAP(X0,Q,Q1)

C
WRITE(6,641) Q
641 FORMAT(IX,'AVERAGE SIGNAL POWER : ',F12.6 )
IF(IR.EQ.2) GO TO 222
IF(IR.GT.2) GO TO 444

C
WRITE(6,66)
66 FORMAT(IX,'ENTER SNR(AVERAGE) IN DECIBEL')
READ(5,*) W1
W3=10.**(W1/10.)
DEV=DSCRT(Q/W3)
GOTO 4111

C
222 WRITE(6,67)
67 FORMAT(IX,'ENTER SNR(PEAK) IN DECIBEL')
READ(5,*) W2
W3=10.**(W2/10.)
DEV=DSCRT(Q1/W3)
GOTO 4111 CONTINUE

C SEED OF RANDOM NOISE GENERATOR WITH UNIFORM DISTRIBUTION
DSEED=12457.D0

C DO NOISE AVERAGING AND ADJUST IF NECESSARY
WRITE(6,68)
68 FORMAT(IX,'ENTER THE NUMBER OF NOISE AVERAGINGS - RECOMMEND:100')
READ(5,*) N2
DO 20 I=1,N2
DO 20 J=1,N2
I=I+1
J=J+1
RANDOM=DMOD(16807.D0*DSEED,02P31M)
RV=DSEED / 02P31

```

```

LGEOC570
LGEOC580
LGEOC590
LGEOC600
LGEOC610
LGEOC620
LGEOC630
LGEOC640
LGEOC650
LGEOC660
LGEOC670
LGEOC680
LGEOC690
LGEOC700
LGEOC710
LGEOC720
LGEOC730
LGEOC740
LGEOC750
LGEOC760
LGEOC770
LGEOC780
LGEOC790
LGEOC800
LGEOC810
LGEOC820
LGEOC830
LGEOC840
LGEOC850
LGEOC860
LGEOC870
LGEOC880
LGEOC890
LGEOC900
LGEOC910
LGEOC920
LGEOC930
LGEOC940
LGEOC950
LGEOC960
LGEOC970
LGEOC980
LGEOC990
LGEOC1000
LGEOC1010
LGEOC1020
LGEOC1030
LGEOC1040
LGEOC1050
LGEOC1060
LGEOC1070
LGEOC1080
LGEOC1090
LGEOC1100
LGEOC1110
LGEOC1120
LGEOC1130
LGEOC1140
LGEOC1150
LGEOC1160
LGEOC1170
LGEOC1180
LGEOC1190
LGEOC1200
LGEOC1210
LGEOC1220
LGEOC1230
LGEOC1240
LGEOC1250
LGEOC1260
LGEOC1270
LGEOC1280
LGEOC1290
LGEOC1300
LGEOC1310
LGEOC1320
LGEOC1330
LGEOC1340
LGEOC1350
LGEOC1360
LGEOC1370
LGEOC1380
LGEOC1390
LGEOC1400
LGEOC1410
LGEOC1420
LGEOC1430
LGEOC1440

```

```

C      GET GCF INDEPENDENT VARIABLE
      RN=RV
      IF(RN.LE-0.5) GCTC 555
      RN=1-RN
      IS1=1
C      CALL TRANF(AGCF,IWA,DEV,RN,X)
C
C      555
      IF(IS1.EQ.0) GOTO 666
      XS=-X
      GCTC 777
      XS=X
      XAO(J)=XNO(J)+X9
      201 CONTINUE
      20 CONTINUE
C      CALL NTEST(IR,W1,W2,Q,Q1,XNO,NFLAG,N2)
C
C      ADC NOISE
      DO 30 I=1,512
      30 X0(I)=X0(I)+XNO(I)
C      CHANGE IF NECESSARY
      CALL HEADER(NT1,NT2,NW1,NW2,ND1,ND2,NF1,ND2)
C      NOISE POLLUTED SIGNAL DISPLAY
      WRITE(6,65)
      65 FORMAT(1X,'DO YOU WANT TO HAVE THE NOISE POLLUTED DATA IN A TABLE
      * FCRM? - <Y/N>')
      READ(5,51) IANS
      IF(IANS.EQ.12) GCTC 9999
C      CALL DISP2(NT1,NT2,NW1,NW2,ND1,ND2,NF1,NF2,N2,T2,S1,X0)
C      C SYNTHETIC DATA STORAGE
C      5111 WRITE(6,71)
      71 FORMAT(1X,'ENTER THE FILE NUMBER OF A DATA FILE INTO WHERE YOU WANT
      *T TO STORE THE DATA',1X,'IF YOU DO NOT WANT TO, ENTER 13,1/')
      ** 1X,1 : HIGH-DAMPING/NOISE-FREE/CONSTANT RESIDUE DATA FILE
      ** 1X,2 : /300DB-SNR /TIME VARYING RESIDUE DATA FILE
      ** 1X,3 : /150DB-SNR /TIME VARYING RESIDUE DATA FILE
      ** 1X,4 : /300DB-SNR /TIME VARYING RESIDUE DATA FILE
      ** 1X,5-6 : NO NOT USE
      ** 1X,7 : LCW-DAMPING/NOISE-FREE/CONSTANT RESIDUE DATA FILE
      ** 1X,8 : /300DB-SNR /TIME VARYING RESIDUE DATA FILE
      ** 1X,9 : /150DB-SNR /TIME VARYING RESIDUE DATA FILE
      ** 1X,1C:

```



CGE01530  
 CGE01540  
 CGE01550  
 CGE01560  
 CGE01570  
 CGE01580  
 CGE01590  
 CGE02000  
 CGE02010  
 CGE02020  
 CGE02030  
 CGE02040  
 CGE02050  
 CGE02060  
 CGE02070  
 CGE02080  
 CGE02090  
 CGE02100  
 CGE02110  
 CGE02120  
 CGE02130  
 CGE02140  
 CGE02150  
 CGE02160  
 CGE02170  
 CGE02180  
 CGE02190  
 CGE02200  
 CGE02210  
 CGE02220  
 CGE02230  
 CGE02240  
 CGE02250  
 CGE02260  
 CGE02270  
 CGE02280  
 CGE02290  
 CGE02300  
 CGE02310  
 CGE02320  
 CGE02330  
 CGE02340  
 CGE02350  
 CGE02360  
 CGE02370  
 CGE02380  
 CGE02390  
 CGE02400

```

C      READ(5,*) IFILE
      IF(IFILE.EQ.13) GO TO 7
      WRITE(IFILE,8) NT1,NT2,NW1,NW2,ND1,ND2,NF1,NF2,N2,I2,S1
8      FORMAT(2X,2A4,/,2X,2A4,/,2X,F14.8,/,2X,F14.8)
      * DO 7 I=1,512,4
        WRITE(IFILE,9) X0(I),X0(I+1),X0(I+2),X0(I+3)
9      FORMAT(2X,4(2X,F14.8))
      CONTINUE
      IF(IFLAG.EQ.0) GO TO 6111
995 CONTINUE
C      111 CONTINUE
C      999$ CONTINUE
C      CALL FRTCMS('CLRSCRN ')
C      WRITE(6,72)
72     FORMAT(IX,////,10X,*** PROCESSING COMPLETED ***)
C      STOP
C      END
=====
= SUBROUTINE HEADER - CAN BE USED WHENEVER USER NEEDS TO CHANGE =
=====
C      SUBROUTINE HEADER(NT1,NT2,NW1,NW2,ND1,ND2,NF1,NF2)
C      IMPLICIT REAL*8(A-H,O-Z)
C      DATA IV,'Y',12,'N'
C      CALL FRTCMS('CLRSCRN ')
C      55 WRITE(6,60) DO YOU WANT TO INITIALIZE/CHANGE THE HEADER? - <Y/N>*
60     FORMAT(IX,20) IANS
      READ(5,20) IANS
      IF(IANS.EQ.12) GO TO 10
      IF(IANS.NE.IV) GO TO 59
C      61 WRITE(6,61) ENTER THE TARGET TYPE WITHIN 8 CHARS*,
61     FORMAT(IX,1X,IGT-1)
      READ(5,51) NT1,NT2
      WRITE(6,62)
62     FORMAT(IX,1X,ENTER THE WAVEFORM TYPE WITHIN 8 CHARS*,
  
```



```

C      IF (IANS.NE.IG) GC TC 2
C      RETURN
C      END
C      =====
C      = SUBROUTINE RPIN - INPUT THE DATA GENERATING PARAMETER
C      =====
C      SUBROUTINE RPIN(ISN1,SRI,SR2,SP1,SP2)
C      IMPLICIT REAL*8(A-H,O-Z)
C      DIMENSION SRI(64),SR2(64),SP1(64),SP2(64)
C      CALL FRICMS('CLRSCRN ')
C      WRITE(6,60)
60  FORMAT(IX,'YOU ARE ASKED TO INPUT INTERACTIVELY THE VALUE OF PARAM
      *ETERS')
C      DO 10 I=1,ISN1
C      WRITE(6,61) I
61  FORMAT(IX,'R-RE(',I2,')=',I2,')
1C  READ(5,*) SRI(I),SR2(I),SP1(I),SP2(I)
C      RETURN
C      END
C      =====
C      = SUBROUTINE DISP1 - TABULATES THE STATUS OF PARAMETERS
C      =====
C      SUBROUTINE DISP1(NSI1,NSI2,NSW1,NSW2,NSD1,NSD2,NSF1,NSF2,
      * NSN1,SRI,SR2,SP1,SP2)
C      IMPLICIT REAL*8(A-H,O-Z)
C      DIMENSION SRI(64),SR2(64),SP1(64),SP2(64)
C      1 CALL FRICMS('CLRSCRN ')
C      WRITE(6,211)
311  FORMAT(IX,'ENTER THE FILE LOCATION INTO WHERE THE POLE AND RESIDUE
      * DATA ARE STORED',
      */,IX,11 : RESERVED FOR HIGH DAMPING DATA',/I
      */,IX,12 : RESERVED FOR LOW DAMPING DATA',/I
C      READ(5,*) IFILE

```



```

C
  2X.5X.03 : NEGATIVE LINEAR.
  2X.5X.04 : TRAPEZOIDAL.
  2X.5X.05 : CONSTANT.
  2X.5X.06 : TRIANGULAR.
  S1=1.
  READ(5,*) M5
  IF(M9.EC.5) GOTC 111
  IF(M9.EC.5) GOTC 999
  WRITE(6,11)
  61 FORMAT(1X,'SPECIFY THE POINT AT WHICH E(K) IS TO BE SET TO ZERO.',
  1X,'RECOMMENDED 10 : WHEN E(K) : A TRAPEZOIDAL.')
  READ(5,*) M3
  GO TO 444
C
  995 M3=1
  888 TO=ST2/511.
C
  T9=0.
  DO 10 I=1,M3
    X9=0.
    X8=C.
    DO 20 J=1,NN1
      XE=SR1(J)*DCQS(2*PI*SP2(J)*T9)-SR2(J)*DSIN(2*PI*SP2(J)*T9)
      X5=X9+X8*DEXP(SPI(J)*T9)
      SXO(I)=X9
      T9=TS+TO
      POWER(I)=X8*2
    10 CONTINUE
    TP=0
    DO 40 I=1,M2
      TP=TF+POWER(I)*2
    40
  4 WRITE(6,73)
  73 FORMAT(1X,'TYPE <8> IF YOU WANT TO CHOOSE ANOTHER OPTION.',
  1X,'OTHERWISE TYPE <G> TO GC.')
  READ(5,*) IANS
  IF(IANS.EQ.18) GO TO 1
  IF(IANS.NE.18) GO TO 4
  CALL FRTCMS('CLRSCRN ')
  IF(M9.EC.5) GO TO 99
  IF(M9.EC.1) GO TO 88
  IF(M9.EC.2) GO TO 77
  IF(M9.EC.3) GO TO 66
  IF(M9.EC.4) GO TO 55
C

```

```

LGEO03E50
LGEO03E60
LGEO03E70
LGEO03E80
LGEO03E90
LGEO03E00
LGEO03E10
LGEO03E20
LGEO03E30
LGEO03E40
LGEO03E50
LGEO03E60
LGEO03E70
LGEO03E80
LGEO03E90
LGEO04C00
LGEO04C10
LGEO04C20
LGEO04C30
LGEO04C40
LGEO04C50
LGEO04C60
LGEO04C70
LGEO04C80
LGEO04C90
LGEO04100
LGEO04110
LGEO04120
LGEO04130
LGEO04140
LGEO04150
LGEO04160
LGEO04170
LGEO04180
LGEO04190
LGEO04200
LGEO04210
LGEO04220
LGEO04230
LGEO04240
LGEO04250
LGEO04260
LGEO04270
LGEO04280
LGEO04290
LGEO04300
LGEO04310
LGEO04320

```

```

C TRIANGULAR FUNCTION OF E(K)
  XTR6=DSCRT(TP/6.)
  SX0(2)=SX0(2) + XTR6
  SX0(3)=SX0(3) + 2*XTR6
  SX0(4)=SX0(4) + XTR6
  GO TO 55

C TRAPEZOIDAL FUNCTION OF E(K)
  55 XTR4=DSCRT(TP/60.)
  SX0(2)=SX0(2) + XTR4
  SX0(3)=SX0(3) + 2*XTR4
  SX0(4)=SX0(4) + 3*XTR4
  SX0(5)=SX0(5) + 4*XTR4
  SX0(6)=SX0(6) + 5*XTR4
  SX0(7)=SX0(7) + 6*XTR4
  SX0(8)=SX0(8) + 7*XTR4
  SX0(9)=SX0(9) + 8*XTR4
  GO TO 55

C NEGATIVE LINEAR FUNCTION OF E(K)
  66 XTR3=DSCRT(TP/30.)
  SX0(1)=SX0(1) + 4*XTR3
  SX0(2)=SX0(2) + 3*XTR3
  SX0(3)=SX0(3) + 2*XTR3
  SX0(4)=SX0(4) + 1*XTR3
  GO TO 55

C
  77 XTR2=DSCRT(TP/30.)
  SX0(2)=SX0(2) + XTR2
  SX0(3)=SX0(3) + 2*XTR2
  SX0(4)=SX0(4) + 3*XTR2
  SX0(5)=SX0(5) + 4*XTR2
  GO TO 55

C DC FUNCTION OF E(K)
  88 XTR1=DSCRT(TP/5.)
  DO 317 I=1,M2
  317 SX0(1)=SX0(1) + XTR1

  95 WRITE(6,62)
  62 FORMAT(IX,'SAMPLING UP TO M3 PCINT COMPLETED...')

C
  MP=M3+1
  DO 30 I=MP,512
  30 X9=C.
  X8=C.
  DO 31 J=1,NN1
  31 XE=SR1(J)*DCOS(2*PI*SP2(J)*T9)-SR2(J)*DSIN(2*PI*SP2(J)*T9)
  X5=X9+X8*LEXP(SPI(J)*T9)
  31

```

```

DGE04330
DGE04340
DGE04350
DGE04360
DGE04370
DGE04380
DGE04390
DGE04400
DGE04410
DGE04420
DGE04430
DGE04440
DGE04450
DGE04460
DGE04470
DGE04480
DGE04490
DGE04500
DGE04510
DGE04520
DGE04530
DGE04540
DGE04550
DGE04560
DGE04570
DGE04580
DGE04590
DGE04600
DGE04610
DGE04620
DGE04630
DGE04640
DGE04650
DGE04660
DGE04670
DGE04680
DGE04690
DGE04700
DGE04710
DGE04720
DGE04730
DGE04740
DGE04750
DGE04760
DGE04770
DGE04780
DGE04790
DGE04800

```



```

C      IMPLICIT REAL*8(A-F,O-Z)
C      DATA IY,Y,IZ,N*/
C      INTEGER IWA,IGA
C      DIMENSION AGDF(5001)
C
C      CALL FRTCMS('CLRSCRN ')
C
C      PI=3.141592654
C      WRITE(6,60)
C      60 FORMAT('X:',ENTER THE NUMBER OF SAMPLING POINTS OF GAUSSIAN PDF *
C      /,'IX:',RECOMMENDED : 5001,(4376 OR 3751:OPTIONAL),)
C      READ(5,*) IWA
C
C      DO 1 I=1,5001
C         AGDF(I)=0.
C
C      IGA=IWA-1
C      RDEL=5./DFLOAT(IGA)
C      RRES=1./DSQRT(2.*PI)
C      AGCF(1)=RRES*EXP(0.)
C      RBAS=RRES
C
C      DO 10 J=2,IWA
C         REXP=RBAS**2./2.
C         AGDF(J)=RRES*DEXP(-REXP)
C         RBAS=RCEL*I
C
C      AFIR=AGCF(1)
C      AGCF(1)=0.5
C      DO 20 J=2,IWA
C         A=AGCF(J)
C         AGDF(J)=AGDF(J-1)+0.5*(AFIR+A)*5./DFLOAT(IGA)
C         AFIR=A
C
C      111 WRITE(6,62) IGA
C      62 FORMAT('IX,IS:',POINTS GAUSSIAN OF WERE EVALUATED',/,'
C      IX:',DO YOU WANT TO SEE F(X) TABLE? - <Y/N>',)
C
C      51 READ(5,*) IANS
C      51 FORMAT('A1')
C      IF(IANS.EQ.IV) GOTC 112
C      IF(IANS.EQ.IZ) GOTO 113
C      GO TO 111
C
C      112 CALL FRTCMS('CLRSCRN ')
C
C      WRITE(6,621)
C      621 FORMAT('2X:',F(X))
C      *F(X)',/,2X,F(X)

```



DGE05770  
DGE05780  
DGE05790  
DGE05800  
DGE05810  
DGE05820  
DGE05830  
DGE05840  
DGE05850  
DGE05860  
DGE05870  
DGE05880  
DGE05890  
DGE05900  
DGE05910  
DGE05920  
DGE05930  
DGE05940  
DGE05950  
DGE05960  
DGE05970  
DGE05980  
DGE05990  
DGE06000  
DGE06010  
DGE06020  
DGE06030  
DGE06040  
DGE06050  
DGE06060  
DGE06070  
DGE06080  
DGE06090  
DGE06100  
DGE06110  
DGE06120  
DGE06130  
DGE06140  
DGE06150  
DGE06160  
DGE06170  
DGE06180  
DGE06190  
DGE06200  
DGE06210  
DGE06220  
DGE06230  
DGE06240

```

*=====*)
K=1
C 114 X1=(K-1)*RDEL
      X2=K*RDEL
      X3=(K+1)*RDEL
      WRITE(6,622) X1,AGDF(K),X2,AGDF(K+1),X3,AGDF(K+2)
      K=K+3
      IF(K.LE.(IGA-2)) GC TO 114
622  FORMAT(1X,F7.3,2X,D10.5,2X,F7.3,2X,D10.5,2X,D10.5)
C 113 CONTINUE
C 222 WRITE(6,63) DO YOU WANT TO STORE THE F(X) TABLE INTO DATA FILE? -
63  *Y/N>
      READ(5,51) IANS
      IF(IANS.EQ.1) GO TO 223
      IF(IANS.EQ.12) GO TO 224
      GO TO 222
C 223 WRITE(8,81) IWA
81  FORMAT(2X,D14.9)
C 40  DO 4C M=1,5000
      WRITE(8,81) AGDF(M)
C 64  WRITE(6,64)
      FORMAT(1X,'DATA WERE STORED...')
C 224 WRITE(6,65)
65  FORMAT(1X,'TYPE <G> TO GO')
      READ(5,51) IANS
      CALL FRICMS('CLRSCRN ')
      RETURN
      END
=====
= SUBROUTINE TRANF - TRANSFORM THE UNIFORM NOISE INTO PSUCO -
= GAUSSIAN NOISE.
=====
C SUBROUTINE TRANF(AGCF,IWA,SDEV,SRN,SX)
C IMPLICIT REAL*4(A-H,O-Z)

```

```

C
DIMENSION AGDF(5001)
IGA=IWA-1
IF(AGDF(I).EQ.SRN) GO TO 99
IF(AGDF(IWA).LE.SRN) GO TO 98
C
L=0
TEMP=164*.2
L2=INT(TEMP)
L1=L2
12 IF(AGDF(L1).EQ.SRN) GOTO 88
IF(AGDF(L1).GT.SRN) GOTO 22
L=L1
L1=L1+L2
GO TO 12
C
22 TEMP=L2*.2
L3=INT(TEMP)
L1=L+L3
23 IF(AGDF(L1).EQ.SRN) GO TO 88
IF(AGDF(L1).GT.SRN) GO TO 33
L=L1
L1=L1+L3
GO TO 23
C
33 TEMP=L3*.2
L4=INT(TEMP)
L1=L+L4
34 IF(AGDF(L1).EQ.SRN) GO TO 88
IF(AGDF(L1).GT.SRN) GO TO 44
L=L1
L1=L1+L4
GO TO 34
C
44 TEMP=L4*.2
L5=INT(TEMP)
L1=L+L5
45 IF(AGDF(L1).EQ.SRN) GOTO 88
IF(AGDF(L1).GT.SRN) GOTO 55
L=L1
L1=L1+L5
GO TO 45
C
55 L1=L+1
56 IF(AGDF(L1).GE.SRN) GOTO 88
L1=L1+1
GO TO 56
C

```

```

DGE06250
DGE06260
DGE06270
DGE06280
DGE06290
DGE06300
DGE06310
DGE06320
DGE06330
DGE06340
DGE06350
DGE06360
DGE06370
DGE06380
DGE06390
DGE06400
DGE06410
DGE06420
DGE06430
DGE06440
DGE06450
DGE06460
DGE06470
DGE06480
DGE06490
DGE06500
DGE06510
DGE06520
DGE06530
DGE06540
DGE06550
DGE06560
DGE06570
DGE06580
DGE06590
DGE06600
DGE06610
DGE06620
DGE06630
DGE06640
DGE06650
DGE06660
DGE06670
DGE06680
DGE06690
DGE06700
DGE06710
DGE06720

```

```

95 SX=0.
GO TO 77

96 SX=SDEV*5.
GO TO 77

98 SX=L1*5./DFLOAT(IGA)*SDEV

77 RETURN
END

=====
= SUBROUTINE CISP2 - DISPLAYS THE DATA SIGNAL IN A TABLE FORM
=====
SUBROUTINE DISP2(NT1,NT2,NW1,NW2,NC1,NC2,NF1,NF2,N2,T2,S1,X0)
IMPLICIT REAL*8(A-T,O-Z)
DIMENSION X0(512)
CALL FRTCMS('CLRSCRN ')
WRITE(6,60) NT1,NT2,NW1,NW2,NC1,NC2,NF1,NF2,N2,T2,S1
60 FORMAT(1X,TARGET TYPE:1,2A4,
//,1X,WAVEFORM TYPE:1,2A4,
//,1X,CONTACT DATE:1,2A4,
//,1X,FILE NUMBER:1,2A4,
//,1X,AVERAGINGS(1):1,2A4,
//,1X,TIME WINDOW:1,2A4,
//,1X,VERTICAL SCALE:1,2A4,/)
WRITE(6,61)
61 FORMAT(1X,2(5X,T:1,4X,5X,2(5X,X(1),4X,5X),
//,1X,2(2X,8(1,1),5X,2X,12(1,1),5X,1))
XDEL=T2/511.
DO 10 I=1,512
XIN(I)=XDEL*(I-1)
XIN(I)=XDEL*I
WRITE(6,62) XIN(I),X0(I),XINT2,X0(I+1)
62 FORMAT(2X,F10.6,5X,F14.8,5X,F10.6,5X,F14.8)
10 CONTINUE
RETURN
END
=====

```

```

C      = SUBROUTINE NTEST - TEST AND ADJUST THE NOISE LEVEL ROUGHFLY =
C      =====
C      SUBROUTINE NTEST(IR,W1,W2,Q,Q1,XNO,NFLAG,N2)
C      IMPLICIT REAL*8(A-H,O-Z)
C      DIMENSION XNO(512)
C      DATA IV,Y,Y1,Z,N//
C      254 NFLAG=C
C      IF(IR.EC.2) GO TO 2
C      POWER=XNO(1)**2
C      DO 10 I=2,512
C      10 POWER = POWER + XNO(I)**2
C      APCWR = POWER/511.
C      RATIO=C/APCWR
C      IF(RATIO.GT.10E+6) RATIO =10E+6
C      SNRDB=10*DLOG10(RATIO)
C      1 WRITE(6,612) N2,SNRDB,W1
C      612 FORMAT(1X,'RESULTED SNR(DB) FOR ',I4,' AVERAGINGS ',F10.6,' DB AGAIN
C      *,1X,'DO YOU WANT TO READJUST THE NOISE LEVEL ',F10.6,' DB
C      *,N<Y/N>')
C      READ(5,51) IANS
C      51 FORMAT(A1)
C      IF(IANS.EC.IZ) GO TO 19
C      IF(IANS.NE.IY) GO TO 1
C      DIF=SNRDB-W1
C      IF(DIF.EC.0.) GC TC 4
C      COEFF=-1./10**(-DIF/20.)
C      GO TO 5
C      4 COEFF= 10**(DIF/20.)
C      5 CONTINUE
C      AMAG=DSCRT(APCWR)
C      BIAS=AMAG*COEFF
C      DO 30 I=1,512
C      30 IF(XNO(I).GE.0.) XNO(I)=XNO(I)+BIAS
C      XNO(1)=XNO(1)-BIAS
C      GO TO 3
C      2 PMAX=XAC(1)**2
C      DO 20 I=2,512
C      20 TMAX=XNO(I)**2
C      2C IF(TMAX.GT.PMAX) PMAX=TMAX
C
C

```





# NON-LINEAR PARAMETER OPTIMIZATION PROGRAM

76







PR0001450  
 PR0001460  
 PR0001470  
 FR0001480  
 PR0001490  
 FR0001500  
 PK0001510  
 PR0001520  
 FK0001530  
 PR0001540  
 FR0001550  
 PR0001560  
 PK0001570  
 FR0001580  
 PR0001590  
 PR0001600  
 FR0001610  
 PR0001620  
 FR0001630  
 PR0001640  
 PR0001650  
 FR0001660  
 PR0001670  
 PR0001680  
 PR0001690  
 PR0001700  
 FR0001710  
 FR0001720  
 PR0001730  
 PR0001740  
 FR0001750  
 PR0001760  
 PK0001770  
 PR0001780  
 FR0001790  
 FR0001800  
 PR0001810  
 FR0001820  
 PR0001830  
 PK0001840  
 PR0001850  
 PR0001860  
 FR0001870  
 PK0001880  
 PR0001890  
 PR0001900  
 PR0001910  
 PR0001920

```

C      WRITE(6,102) IO,X(I),X(I+1),X(I+2),X(I+3)
C      FORMAT(2X,I4,3X,4(F14.8,1X))
C      CONTINUE
C      IF(NEL.EQ.0) GO TO 105
C      WRITE(IFILE,103)
C      WRITE(6,103)
C      FORMAT(1X,//,2X,B.OPTIMIZED VALUE OF E(K)',
C      *//,2X,'-----')
C      DO 50 I=1,NEL
C      IO=IC+I
C      K=N1+I
C      WRITE(IFILE,104) IO,X(K)
C      WRITE(6,104) IO,X(K)
C      FORMAT(2X,E(' ,12',')=',F14.8)
C      CONTINUE
C      NEL=NEL+1
C      DO 90 I=1,NEL
C      X(N1+I)=0
C      CONTINUE
C      IF(NEL.CE.M3) GO TO 1001
C      WRITE(6,1003)
C      FORMAT(1X,'IF YOU READY TO GO, TYPE ANY CHAACTER.')
C      READ(5,F1) JANS
C      GO TO 1234
C      CONTINUE
C      PUT TERMINATE
C      1001 WRITE(6,1000)
C      1000 FORMAT(1X,10X,'*** PROCESSING COMPLETED ***')
C      STCP
C      END
=====
SUBROUTINE PARAS - DETERMINE THE NUMBER OF PARAMETERS
                     A(N),B(N),SIGMA(N),FREQ(N)
                     E(1)..E(INTO-1)
SPECIFY THE DATA PCINT AT WHICH E(K)
ASSUMED TO BE ZERO(M3 PCINTS)
=====
SUBROUTINE PARAS(M3,N1,NEL)

```

```

C      IMPLICIT REAL*8(A-H,O-Z)
C      DATA IG/'G',IB/'B'/
C      1 CALL FRICMS('CLRSCRN ')
C      WRITE(6,61)
C      READ(5,*) N1
C      WRITE(6,62)
C      READ(5,*) N1
C      WRITE(6,63)
C      READ(5,*) M3
C      61 FORMAT(1X,'ENTER THE NUMBER OF POLES OF THE RESPONSE (# OF POLES)')
C      62 FORMAT(1X,'HOW MANY EARLY TIME DATA POINTS DO YOU WANT TO HAVE?')
C      63 FORMAT(1X,'IN YOUR CURRENT DATA WINDOW? : 0 UP TO 10 (MAX)')
C      64 FORMAT(1X,'SPECIFY K* POINT AT WHICH E(K) IS ASSUMED TO BE ZERO')
C      65 FORMAT(1X,'MATCH IT TO YOU K* OF YOUR DATA GENERATION ROUTINE')
C      66 FORMAT(1X,'MATCH IT TO YOU K* OF YOUR DATA GENERATION ROUTINE')
C      CHANGE IF NECESSARY
C      2 WRITE(6,64)
C      64 FORMAT(1X,'TYPE <B> TO GO BACK TO CHANGE THE ABOVE VARIABLES')
C      65 FORMAT(1X,'OTHERWISE TYPE <G> TO GO')
C      66 FORMAT(1X,'OTHERWISE TYPE <G> TO GO')
C      51 READ(5,*) IANS
C      52 FORMAT(1X,'IF (IANS.EQ.1) GO TO 1')
C      53 IF (IANS.EQ.1) GO TO 1
C      54 IF (IANS.NE.1) GO TO 2
C      RETURN
C      END
C      =====
C      = SUBROUTINE INGU : INPUT THE INITIAL TRIALS FOR THE UNKNOWNNS
C      =====
C      SUBROUTINE INGU(X,N,N1,N1)
C      IMPLICIT REAL*8(A-H,O-Z)
C      DATA IY/'Y',IZ/'Z'/
C      DIMENSION X(N)
C      1 CALL FRICMS('CLRSCRN ')
C      WRITE(6,61)
C      61 FORMAT(1X,'ENTER THE INITIAL VALUE OF THE X(K) PARAMETERS')
C      10=0
C      DO 10 I=1,N1,4

```

```

PR002410
PR002420
PR002430
PR002440
PR002450
PR002460
PR002470
PR002480
PR002490
PR002500
PR002510
PR002520
PR002530
PR002540
PR002550
PR002560
PR002570
PR002580
PR002590
PR002600
PR002610
PR002620
PR002630
PR002640
PR002650
PR002660
PR002670
PR002680
PR002690
PR002700
PR002710
PR002720
PR002730
PR002740
PR002750
PR002760
PR002770
PR002780
PR002790
PR002800
PR002810
PR002820
PR002830
PR002840
PR002850
PR002860
PR002870
PR002880

```



[illegible]



```

PR004330
PR004340
PR004350
PR004360
PR004370
PR004380
PR004390
PR004400
PR004410
PR004420
PR004430
PR004440
PR004450
PR004460
PR004470
PR004480
PR004490
PR004500
PR004510
PR004520
PR004530
PR004540
PR004550
PR004560
PR004570
PR004580
PR004590
PR004600
PR004610
PR004620
PR004630
PR004640
PR004650
PR004660
PR004670
PR004680
PR004690
PR004700
PR004710
PR004720
PR004730
PR004740
PR004750
PR004760
PR004770
PR004780
PR004790
PR004800

```

# INITIALIZE VARIABLES

```

C
ISCALL = ISCALL+1
ISCALLU = ISCALL+N
IXNEW1 = IXNEW1+1
IXNEW1+N
IXBAD1 = IXBAD1+N
IFPL1 = IFPL1+1
IFPL1+N
IFPL1 = IFPL1+M
IFPL1+N
IFML1 = IFML1+1
IFML1+N
IMJC = IXJAC - M

AL = CNE
CONS2 = TENTH
IF (IOPT.EQ.0) GO TO 20
IF (IOPT.EQ.1) GO TO 10
AL = PARM(1)
FO = PARM(2)
UP = PARM(3)
CONS2 = PARM(4)*HALF
GO TO 15

1C AL = PC1
FO = TMC
UP = HLAT#
ONESFO = ONE/FO
FOSQ = FO*FO
FOSQS4 = FOSQ**4
20 IEVAL = 0
DELTA2 = DELTA*HALF
ERL2 = CNEP10
IBAD = -99
IS# = 1
ITER = -1
INFER = 0
IER = C
DO 25 J=IDELXL, IDELXU
  WORK(J) = ZERO
25 CONTINUE
GO TO 165

C 3C SSQOLD = SSQ
C
C IF (INFER.GT.0.OR. IJAC.GE.N.OR. IJACOUNT.GT.0) GO TO 55
  IJAC = IJAC+1
  USQ = ZERO
  DO 35 J=IDELXL, IDELXU
    DSQ = DSQ+WORK(J)*WCRK(J)
  35

```

# MAIN LOOP

CALCULATE JACOBIAN  
RANK ONE UPDATE TO JACOBIAN



```

FR004810
FR004820
FR004830
FR004840
FR004850
FR004860
FR004870
FR004880
FR004890
FR004900
FR004910
FR004920
FR004930
FR004940
FR004950
FR004960
FR004970
FR004980
FR004990
FR005000
FR005010
FR005020
FR005030
FR005040
FR005050
FR005060
FR005070
FR005080
FR005090
FR005100
FR005110
FR005120
FR005130
FR005140
FR005150
FR005160
FR005170
FR005180
FR005190
FR005200
FR005210
FR005220
FR005230
FR005240
FR005250
FR005260
FR005270
FR005280

```

```

35 CONTINUE
IF (DSC.LE.ZERO) GC TO 55
DO 50 I=1,M
G = F(I)-WORK(IFMLI+I)
K = I
DO 40 J=IDELXL, IDELXU
G = G+XJAC(K)*WORK(J)
K = K+IXJAC
CONTINUE
G = G/DSC
K = I
DO 45 J=IDELXL, IDELXU
XJAC(K) = XJAC(K)-G*WORK(J)
K = K+IXJAC
CONTINUE
50 CONTINUE
GO TO 80

C 55 IJAC = C
K = -IJAC
DO 75 J=1,N
K = K+IJAC
XDABS = DABS(X(J))
HH = REL*(DMAX1(XDABS,AX))
XHOLD = X(J)
X(J) = X(J)+FH

JACOBIAN BY INCREMENTING X

C CALL FUNC
CALL FUNC (X,M,N,WORK(IFPL),T2,M3,N1,NE1)
IEVAL = IEVAL+I
X(J) = XFOLD
IF (ISW.EQ.1) GC TO 65

CENTRAL DIFFERENCES

C X(J) = XHOLD-FH
C CALL FUNC
CALL FUNC (X,M,N,WORK(IFML),T2,M3,N1,NE1)
IEVAL = IEVAL+I
X(J) = XFOLD
RHH = HALF/HH
DO 60 I=IFPL,IFPU
K = K+I
XJAC(K) = (WORK(I)-WORK(I+M))*RHH
CONTINUE
GO TO 75

60 CONTINUE

C 65 RHH = ONE/HH
DO 7C I=1,M

FORWARD DIFFERENCES

```

```

      K = K+1
      XJAC(K) = (WCRK(IFPL1+1)-F(1))*RHF
      CONTINUE
75 CONTINUE
      C
      80 ERL2X = ERL2
      ERL2 = ZERO
      K = -1
      DO 90 J=1,GRADL,IGRADU
        K = K+1
        SUM = ZERO
        DO 85 I=1,M
          K = K+1
          SUM = SUM+XJAC(K)*F(I)
        CONTINUE
      WORKK(J) = SUM
      ERL2 = ERL2+SUM*SUM
      90 CONTINUE
      ERL2 = CSQRT(ERL2)
      C
      IF (IJAC.GT.0) GO TO 95
      IF (ERL2.LE.DELTA2) INFER = INFER+4
      IF (ERL2.LE.CONVS2) ISW = 2
      C
      95 L = 0
      IS = -IXJAC
      DO 110 I=1,N
        IS = IS+IXJAC
        JS = -IXJAC
        DO 105 J=1,I
          JS = JS+IXJAC
          L = L+1
          SUM = ZERO
          CC 100 K=1,M
            LJ = IS+K
            SUM = SUM+XJAC(LJ)*XJAC(LJ)
          CONTINUE
        XJJ(L) = SUM
      CONTINUE
      105 CONTINUE
      110 CONTINUE
      C
      IF (INFER.GT.0) GO TO 315
      IF (IEVAL.GE.MAXFN) GO TO 290
      C
      IF (IGFT.EQ.0) GO TO 120
      K = 0
      C
      115 CONTINUE
      120 CONTINUE
      C
      130 CONTINUE
      140 CONTINUE
      150 CONTINUE
      160 CONTINUE
      170 CONTINUE
      180 CONTINUE
      190 CONTINUE
      200 CONTINUE
      210 CONTINUE
      220 CONTINUE
      230 CONTINUE
      240 CONTINUE
      250 CONTINUE
      260 CONTINUE
      270 CONTINUE
      280 CONTINUE
      290 CONTINUE
      300 CONTINUE
      310 CONTINUE
      320 CONTINUE
      330 CONTINUE
      340 CONTINUE
      350 CONTINUE
      360 CONTINUE
      370 CONTINUE
      380 CONTINUE
      390 CONTINUE
      400 CONTINUE
      410 CONTINUE
      420 CONTINUE
      430 CONTINUE
      440 CONTINUE
      450 CONTINUE
      460 CONTINUE
      470 CONTINUE
      480 CONTINUE
      490 CONTINUE
      500 CONTINUE
      510 CONTINUE
      520 CONTINUE
      530 CONTINUE
      540 CONTINUE
      550 CONTINUE
      560 CONTINUE
      570 CONTINUE
      580 CONTINUE
      590 CONTINUE
      600 CONTINUE
      610 CONTINUE
      620 CONTINUE
      630 CONTINUE
      640 CONTINUE
      650 CONTINUE
      660 CONTINUE
      670 CONTINUE
      680 CONTINUE
      690 CONTINUE
      700 CONTINUE
      710 CONTINUE
      720 CONTINUE
      730 CONTINUE
      740 CONTINUE
      750 CONTINUE
      760 CONTINUE

```

PR005770  
 PR005780  
 PR005790  
 PR005800  
 PR005810  
 PR005820  
 PR005830  
 PR005840  
 PR005850  
 PR005860  
 PR005870  
 PR005880  
 PR005890  
 PR005900  
 PR005910  
 PR005920  
 PR005930  
 PR005940  
 PR005950  
 PR005960  
 PR005970  
 PR005980  
 PR005990  
 PR006000  
 PR006010  
 PR006020  
 PR006030  
 PR006040  
 PR006050  
 PR006060  
 PR006070  
 PR006080  
 PR006090  
 PR006100  
 PR006110  
 PR006120  
 PR006130  
 PR006140  
 PR006150  
 PR006160  
 PR006170  
 PR006180  
 PR006190  
 PR006200  
 PR006210  
 PR006220  
 PR006230  
 PR006240

```

      DO 115 J=1,N
        K = K+J
        WORK(ISCAL1+J) = XJTJ(K)
      115 CONTINUE
      GO TO 135
C
      120 DNORM = ZERO
      K = 0
      DO 125 J=1,N
        K = K+J
        WORK(ISCAL1+J) = DSQRT(XJTJ(K))
        DNORM = DNORM+XJTJ(K)*XJTJ(K)
      125 CONTINUE
      DNORM = ONE/DSQRT(DNORM)
C
      DO 130 J=ISCAL1,ISCALU
        WORK(J) = WORK(J)*DNORM*ERL2
      130 CONTINUE
C
      135 ICOLNT = 0
      140 K = 0
      DO 150 J=1,N
        DO 145 J=1,I
          K = K+1
          WORK(K) = XJTJ(K)
        CONTINUE
        WORK(K) = WORK(K)+WORK(ISCAL1+I)*AL
        WORK(IDELX1+I) = WORK(IGRAD1+I)
      150 CONTINUE
C
      155 CALL LECTIP (WORK,1,N,WORK(IDELX1),N,0,C,XHCLD,IER)
      IER = C
      IF (IER.EQ.0) GO TO 160
      IF (I JAC.GT.0) GO TO 55
      IF (IBAL.LE.0) GO TO 240
      IF (IBAL.GE.2) GO TO 310
      GO TO 190
      160 IF (IBAL.NE.-99) IBAD = 0
C
      165 DO 170 J=1,N
        WORK(IXNEW1+J) = X(J)-WORK(IDELX1+J)
      170 CONTINUE
C
      CALL FUNC
      CALL FUNC (WORK(IXNEW1),M,N,WORK(IFPL),T2,M3,N1,NE1)
      IEVAL = IEVAL+1
      SSC = ZERO
      DO 175 I=IFPL,IFPU

```

PR006250  
 PR006260  
 PR006270  
 PR006280  
 PR006290  
 PR006300  
 PR006310  
 PR006320  
 PR006330  
 PR006340  
 PR006350  
 PR006360  
 PR006370  
 PR006380  
 PR006390  
 PR006400  
 PR006410  
 PR006420  
 PR006430  
 PR006440  
 PR006450  
 PR006460  
 PR006470  
 PR006480  
 PR006490  
 PR006500  
 PR006510  
 PR006520  
 PR006530  
 PR006540  
 PR006550  
 PR006560  
 PR006570  
 PR006580  
 PR006590  
 PR006600  
 PR006610  
 PR006620  
 PR006630  
 PR006640  
 PR006650  
 PR006660  
 PR006670  
 PR006680  
 PR006690  
 PR006700  
 PR006710  
 PR006720

```

175 CONTINUE
176 IF (ITER.GE.0) GO TO 185
C
C      SSG FOR INITIAL ESTIMATES OF X
      ITER = C
      SSCOLD = SSG
      DO 180 I=1,M
        F(I) = WCRK(IFPL1+I)
180 CONTINUE
      GO TO 185
185 IF (IOPT.EQ.0) GO TO 215
C
C      CHECK DESCENT PROPERTY
      IF (SSQ.LE.SSQOLD) GO TO 205
C
C      INCREASE PARAMETER AND TRY AGAIN
      ICOUNT = ICOUNT+1
      AL = AL*FOSC
      IF (IJAC.EQ.0) GC TO 195
      IF (ICOUNT.GE.4.OR.AL.GT.UP) GC TO 200
195 IF (AL.LE.UP) GC TO 140
      IF (IBAL.EQ.1) GO TO 310
      IER = 35
      GO TO 315
200 AL = AL/FOSCS4
      GO TO 185
C
C      ADJUST MARQUARDT PARAMETER
205 IF (ICOUNT.EQ.0) AL = AL/F0
      IF (ERL2X.LE.ZERO) GO TO 210
      G = (ERL2X/ERL2X)
      IF (ERL2.LT.ERL2X) AL = AL*DMAX1(ONESFO,G)
      IF (ERL2.GT.ERL2X) AL = AL*DMIN1(F0,G)
210 AL = DMAX1(AL,PREC)
C
C      ONE ITERATION CYCLE COMPLETED
215 ITER = ITER+1
      DO 220 J=1,N
        X(J) = WCRK(IXNEW1+J)
220 CONTINUE
      DO 225 I=1,M
        WORK(IFML1+I) = F(I)
        F(I) = WCRK(IFPL1+I)
225 CONTINUE
C
C      RELATIVE CONVERGENCE TEST FOR X
      IF (AL.GT.5.0D0) GO TO 30
      DO 230 J=1,N
        XDIF = DABS(WORK(IDELX1+J))/DMAX1(DABS(X(J)),AX)
        IF (XDIF.GT.RELCON) GO TO 255
230 CONTINUE
      INFER = 1
C
C      RELATIVE CONVERGENCE TEST FOR SSG

```

```

235 SQDIFF = DABS(SSQ-SQGLD1)/DMAX1(SSQCLD,AX)
   IF (SQDIFF.LE.EPS) INFER = INFER+2
   GO TO 3C
C
240 IF (IBAD) 255,245,265
C
C     SINGULAR DECOMPOSITION
C     CHECK TO SEE IF CURRENT
C     ITERATE HAS CYCLED BACK TO
C     THE LAST SINGULAR POINT
245 DO 250 J=1,N
   XHOLD = WORK(IXBAD1+J)
   IF (DABS(X(J)-XHOLD).GT.RELCON*DMAX1(AX,DABS(XHOLD))) GO TO 255
250 CONTINUE
   GO TO 255
C
255 DO 260 J=1,N
   WORK(IXBAD1+J) = X(J)
260 CONTINUE
   IBAD = 1
C
265 IF (IOPT.NE.0) GO TO 280
   K = 0
   DO 275 I=1,N
     DO 270 J=1,I
       K = K+1
       WORK(K) = XJTJ(K)
270 CONTINUE
       WORK(K) = ONEP5*(XJTJ(K)+AL*ERL2*WORK(ISCAL1+J))+REL
275 CONTINUE
   IBAD = 2
   GO TO 155
C
280 IZERO = 0
   DO 285 J=ISCAL1,ISCALU
     IF (WORK(J).GT.ZERC) GO TO 285
     IZERC = IZERC+1
     WORK(J) = ONE
285 CONTINUE
   IF (IZERC.LT.N) GO TO 140
   IER = 36
   GO TO 315
C
290 IER = IER+1
295 IER = IER+1
305 IER = IER+1
310 IER = IER+129
   IF (IER.EQ.130) GO TO 335
C
C     OUTPUT ERL2,IEVAL,NSIG,AL, AND ITER

```

```

PR006730
PR006740
PR006750
PR006760
PR006770
PR006780
PR006790
PR006800
PR006810
PR006820
PR006830
PR006840
PR006850
PR006860
PR006870
PR006880
PR006890
PR006900
PR006910
PR006920
PR006930
PR006940
PR006950
PR006960
PR006970
PR006980
PR006990
PR007000
PR007010
PR007020
PR007030
PR007040
PR007050
PR007060
PR007070
PR007080
PR007090
PR007100
PR007110
PR007120
PR007130
PR007140
PR007150
PR007160
PR007170
PR007180
PR007190
PR007200

```

```

315 G = SIG
DO 320 J=1,N
  XHOLD = DABS(WORK(IDELX1+J))
  IF (XFOLC.LE.ZERC) GO TO 320
  G = CMINI(G,-DLOG10(XHOLD)+DLOG10(DMAX1(AX,DABS(X(J))))))
320 CONTINUE
  IF (N.GT.2) GO TO 330
  DO 325 J=1,N
    WORK(J+5) = WORK(J+IGRAD1)
325 WORK(1) = ERL2+ERL2
330 WORK(2) = IEVAL
    SSC = SCGLC
    WORK(3) = G
    WORK(4) = AL
    WORK(5) = ITER
335 CALL UEFSET(LEVOLD,LEVCLD)
900C IF (IER.EQ.0) GO TO 9005
    CALL UEFST (IER,6HZSSQ)
9005 RETURN
    END
=====
SUBROUTINE LEQTP
PURPOSE
=====
- LINEAR EQUATION SOLUTION - POSITIVE DEFINITE
  MATRIX - SYMMETRIC STORAGE MODE - SPACE
  ECUNGMIZER SOLUTION
=====
SUBROUTINE LEQTP (A,M,N,B,IB,IDGT,D1,D2,IER)
  DIMENSION A(1),B(18,1)
  DOUBLE PRECISION A,B,D1,D2
  FIRST EXECUTABLE STATEMENT
  INITIALIZE IER
  DECOMPOSE A
  PERFORM ELIMINATION
  DO 5 I=1,M
    CALL LUCECP (A,A,N,D1,D2,IER)
    IF (IER.NE.0) GO TO 9000
  5 CONTINUE
  GO TO 9005
900C CONTINUE
9005 CALL UEFST(IER,6HLEQTP)
    RETURN
    END
=====

```

```

315 G = SIG
DO 320 J=1,N
  XHOLD = DABS(WORK(IDELX1+J))
  IF (XHOLD.LE.ZERO) GO TO 320
  G = CMIN1(G,-DLOG10(XHOLD)+DLOG10(DMAX1(AX,DABS(X(J))))))
320 CONTINUE
  IF (N.GT.2) GO TO 330
  DO 325 J=1,N
    WORK(J+5) = WORK(J+IGRAD1)
325 WORK(1) = ERL2+ERL2
330 WORK(2) = IEVAL
    SSC = SSCCLD
    WORK(3) = G
    WORK(4) = AL
    WORK(5) = ITER
335 CALL UEFSET(LEVOLD,LEVCLD)
    IF (IER.EQ.0) GO TO 9005
9000 CONTINUE
    CALL UEFIST (IER,6HZXSQ)
9005 RETURN
    END
=====
C SUBROUTINE LEQTP
C PURPOSE
C -- LINEAR EQUATION SOLUTION - POSITIVE DEFINITE
C MATRIX - SYMMETRIC STORAGE MODE - SPACE
C ECONOMIZER SOLUTION
C =====
C SUBROUTINE LEQTP (A,M,N,B,IB,IDGT,D1,D2,IER)
C
C DIMENS(CN A(1),P(IB,1)
C DOUBLE PRECISION A,B,D1,D2
C
C IER = 0
C FIRST EXECUTABLE STATEMENT
C INITIALIZE IER
C DECOMPOSE A
C CALL LUCECP (A,A,N,D1,D2,IER)
C IF (IER.NE.0) GO TO 9000
C
C DO 5 I=1,M
C   CALL LUZLMP (A,B(1,I),N,B(1,I))
C   CONTINUE
C   GO TO 5005
C 9000 CONTINUE
C   CALL UEFIST(IER,6HLEQTP)
C 9005 RETURN
C   END
=====

```

```

FR007210
FR007220
FR007230
FR007240
FR007250
FR007260
FR007270
FR007280
FR007290
FR007300
FR007310
FR007320
FR007330
FR007340
FR007350
FR007360
FR007370
FR007380
FR007390
FR007400
FR007410
FR007420
FR007430
FR007440
FR007450
FR007460
FR007470
FR007480
FR007490
FR007500
FR007510
FR007520
FR007530
FR007540
FR007550
FR007560
FR007570
FR007580
FR007590
FR007600
FR007610
FR007620
FR007630
FR007640
FR007650
FR007660
FR007670
FR007680

```

```

C C C C C C C
=====
SUBROUTINE LUDECP
PURPOSE      - DECOMPOSITION OF A POSITIVE DEFINITE MATRIX -
              SYMMETRIC STORAGE MCODE
=====
SUBROUTINE LUDECP (A,UL,N,D1,D2,IER)
DIMENSION    A(1),UL(1)
DOUBLE PRECISION
DATA         A,ZERO,ONE,FOUR,SIXTN,SIXTH,X,RN
              0.000,1.00,4.00,16.00,0.0625D0/
              * FIRST EXECUTABLE STATEMENT
D1=ONE
D2=ZERO
RN = ONE/(N*SIXTN)
IP = 1
IER=0
DO 45 I = 1,N
  IQ = 1
  IR = 1
  DO 4C J = 1,I
    X = A(IP,I)
    IF (J.EQ.1) GO TO 10
    CC 5 K=IQ,IPI
    X = X - UL(K) * UL(IR)
    IR = IR+1
  CCNTINUE
  IF (I.NE.J) GO TO 30
  C1 = D1*X
  IF (A(IP,I) + X*RN.LE.A(IP)) GO TC 50
  IF (DABS(C1).LE.ONE) GO TO 20
  C1 = D1 * SIXTH
  C2 = D2 + FOUR
  CC TO 15
  IF (DABS(D1).GE.SIXTH) GO TC 25
  C1 = D1 * SIXTN
  C2 = C2 - FOUR
  CC TO 20
  UL(IP) = CNE/DSQRT(X)
  CC TO 35
  UL(IP) = X * UL(IR)
  IF1 = IP+1
  IF = IR+1
  IR = IR+1
  CCNTINUE
  45 CONTINUE
  4C CONTINUE

```





```

T = T - A(1S) * X(KK)
KK = KK - 1
IS = IS - KK
CONTINUE
X(11) = T * A(1S)
CONTINUE
RETURN
END
=====
SUBROUTINE UERSET
PURPOSE - SET MESSAGE LEVEL FOR IMPL ROUTINE UERTST
MSG :
=====
LEVEL = 4 CAUSES ALL MESSAGES TO BE
PRINTED;
LEVEL = 3 MESSAGES ARE PRINTED IF IER IS
GREATER THAN 32;
LEVEL = 2 MESSAGES ARE PRINTED IF IER IS
GREATER THAN 64;
LEVEL = 1 MESSAGES ARE PRINTED IF IER IS
GREATER THAN 128;
LEVEL = 0 ALL MESSAGE PRINTING IS
SUPPRESSED.
=====
SUBROUTINE UERSET (LEVEL, LEVOLD)
INTEGER LEVEL, LEVOLD
SPECIFICATIONS FOR ARGUMENTS
LEVOLD = LEVEL
FIRST EXECUTABLE STATEMENT
CALL UERTST (LEVOLD, 6HUSERSET)
RETURN
END
=====
SUBROUTINE UERTST
PURPOSE - PRINT A MESSAGE REFLECTING AN ERROR CONDITION
=====
ARGUMENTS : IER - ERROR PARAMETER. (INPUT)
IER = I + J WHERE
I = 128 IMPLIES TERMINAL ERROR MESSAGE,
I = 64 IMPLIES WARNING WITH FIX MESSAGE,
J = 32 IMPLIES WARNING MESSAGE,
J = ERROR CODE RELEVANT TO CALLING
ROUTINE.
NAME - A CHARACTER STRING OF LENGTH SIX PROVIDING
THE NAME OF THE CALLING ROUTINE. (INPUT)
=====
SUBROUTINE UERTST (IER, NAME)

```

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AD-A139 027

INVESTIGATION OF NON-LINEAR ESTIMATION OF NATURAL  
RESONANCES IN TARGET IDENTIFICATION(U) NAVAL  
POSTGRADUATE SCHOOL MONTEREY CA C Y CHONG DEC 83

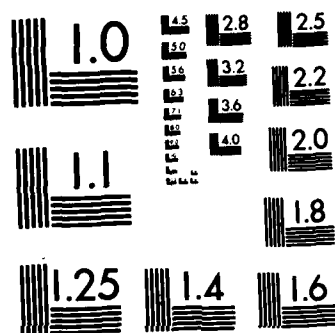
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NL





MICROCOPY RESOLUTION TEST CHART  
NATIONAL BUREAU OF STANDARDS-1963-A

```

C      INTEGER      IER
C      INTEGER      NAME(1)
C
C      INTEGER      I, IEQ, IEQDF, IOUNIT, LEVEL, LEVOLD, NAMEQ(6),
C      *      NAMESET(16), NAMUPK(6), NIN, NMTB
C      DATA      NAMESET/1HU,1HE,1HR,1HS,1HE,1HT/
C      DATA      NAMEQ/6*IH/
C      DATA      LEVEL/4*,IEQDF/0/,IEQ/1H=/,
C      C      CALL USPXD (NAME,6,NAMUPK,NMTB)
C      C      CALL UGETIO(1,NIN,ICUNIT)
C      C      IF (IER.GT.999) GO TO 25
C      C      IF (IER.LT.-32) GO TO 55
C      C      IF (IER.LE.128) GO TO 5
C      C      IF (LEVEL.LT.1) GO TO 30
C
C      IF (IECCF.EQ.1) WRITE( IOUNIT,35) IER,NAMEQ,IEQ,NAMUPK
C      IF (IECCF.EQ.0) WRITE( IOUNIT,35) IER,NAMUPK
C      GO TO 3C
C      5 IF (IER.LE.64) GO TO 10
C      IF (LEVEL.LT.2) GO TO 30
C
C      IF (IECCF.EQ.1) WRITE( IOUNIT,40) IER,NAMEQ,IEQ,NAMUPK
C      IF (IECCF.EQ.0) WRITE( IOUNIT,40) IER,NAMUPK
C      GO TO 3C
C      1C IF (IER.LE.32) GO TO 15
C      IF (LEVEL.LT.3) GO TO 30
C      IF (IECCF.EQ.1) WRITE( IOUNIT,45) IER,NAMEQ,IEQ,NAMUPK
C      IF (IECCF.EQ.0) WRITE( IOUNIT,45) IER,NAMUPK
C      GO TO 3C
C      15 CONTINUE
C
C      DO 20 I=1,6
C      IF (NAMUPK(I).NE.NAMESET(I)) GO TO 25
C      20 CONTINUE
C      LEVOLD = LEVEL
C      LEVEL = IER
C      IF (LEVEL.LT.0) LEVEL = 4
C      IF (LEVEL.GT.4) LEVEL = 4
C      GO TO 3C
C      25 CONTINUE
C      IF (LEVEL.LT.4) GO TO 30

```

```

C      IF (IEQCF.EQ.1) WRITE(IOUNIT,50) IER,NAMEQ,IEQ,NAMUPK
      IF (IEQCF.EQ.0) WRITE(IOUNIT,50) IER,NAMUPK
      IEQCF = 0
      30 RETURN
      35 FORMAT(15H *** TERMINAL ERROR,10X,7H( IER = ,I3,
1      40 FROM I MSL ROUTINE,6A1,A1,6A1)
      40 FORMAT(27H *** WARNING WITH FIX ERACR,2X,7H( IER = ,I3,
1      45 FROM I MSL ROUTINE,6A1,A1,6A1)
      45 FORMAT(18H *** WARNING ERROR,11X,7H( IER = ,I3,
1      50 FROM I MSL ROUTINE,6A1,A1,6A1)
      50 FORMAT(20H *** UNDEFINED ERROR,9X,7H( IER = ,I5,
1      1 FROM I MSL ROUTINE,6A1,A1,6A1)

C      SAVE P FOR P = R CASE
C      P IS THE PAGE NAMUPK
C      R IS THE ROUTINE NAMUPK

      55 IEQDF = 1
      DO 60 I=1,6
      60 NAMEQ(I) = NAMUPK(I)
      65 RETURN
      65 ENC

=====
SUBROUTINE UGETIO
PURPOSE      - TO RETRIEVE CURRENT VALUES AND TO SET NEW
              VALUES FOR INPUT AND OUTPUT UNIT IDENTIFIERS.
=====
ARGUMENTS    IOPT      - OPTION PARAMETER. (INPUT)
              1. IF IOPT=1, THE CURRENT INPUT AND OUTPUT
              AND NOUT IDENTIFIERS ARE RETURNED IN NIN
              AND NOUT, RESPECTIVELY.
              2. IF IOPT=2, THE INTERNAL VALUE OF NIN IS
              RESET FOR SUBSEQUENT USE.
              3. IF IOPT=3, THE INTERNAL VALUE OF NOUT IS
              RESET FOR SUBSEQUENT USE.
              NIN      - INPUT UNIT IDENTIFIER.
              NOUT     - OUTPUT UNIT IDENTIFIER.
              OUTPUT IF IOPT=1, INPUT IF IOPT=2.
              OUTPUT IF IOPT=1, INPUT IF IOPT=3.

SUBROUTINE UGETIO( ICPT,NIN,NOUT)
SPECIFICATIONS FOR ARGUMENTS
INTEGER      IOPT,NIN,NOUT
SPECIFICATIONS FOR LOCAL VARIABLES
INTEGER      NIND,NOUTD
DATA         NIND/57,NOUTD/6/
FIRST EXECUTABLE STATEMENT
=====

```

```

PR00$610
PR00$620
PR00$630
PR00$640
PR00$650
PR00$660
PR00$670
PR00$680
PR00$690
PR00$700
PR00$710
PR00$720
PR00$730
PR00$740
PR00$750
PR00$760
PR00$770
PR00$780
PR00$790
PR00$800
PR00$810
PR00$820
PR00$830
PR00$840
PR00$850
PR00$860
PR00$870
PR00$880
PR00$890
PR00$900
PR00$910
PR00$920
PR00$930
PR00$940
PR00$950
PR00$960
PR00$970
PR00$980
PR00$990
PR010000
PR010010
PR010020
PR010030
PR010040
PR010050
PR010060
PR010070
PR010080

```

```

IF (IOPT1.EQ.3) GO TO 10
IF (IOPT1.EQ.2) GO TO 5
IF (IOPT1.NE.1) GO TO 9005
NIN = NIAD
NOUT = AOUTD
GO TO SC05
= NIND = NIN
GO TO SC05
10 NOUTD = NOUT
9005 RETURN
END

=====
SUBROUTINE USCKED
PURPOSE - NUCLEUS CALLED BY IMSL FCUTINES THAT HAVE
CHARACTER STRING ARGUMENTS
=====
ARGUMENTS
PACKED - CHARACTER STRING TO BE UNPACKED. (INPUT)
NCHARS - LENGTH OF PACKED. (INPUT) SEE REMARKS.
UNPAKD - INTEGER ARRAY TO RECEIVE THE UNPACKED
REPRESENTATION OF THE STRINGS. (OUTPUT)
NCHMTB - NCHARS MINUS TRAILING BLANKS. (OUTPUT)
APPLIED TO THIS CODE. NO OTHER WARRANTY.
EXPRESSED OR IMPLIED; IS APPLICABLE.
=====
SUBROUTINE USPKD (PACKED,NCHARS,UNPAKD,NCHMTB)
INTEGER NC,NCHARS,NCHMTB
SPECIFICATIONS FOR ARGUMENTS
LOGICAL*1 UNPAKD(1),PACKED(1),LBYTE,LBLANK
INTEGER*2 IBYTE,IBLANK
EQUIVALENCE (LBYTE,IBYTE)
DATA IBLANK /1H /
DATA IBLANK /1H /
DATA IBLANK /1H /
INITIALIZE NCHMTB
NCHMTB = 0
IF (NCHARS.LE.0) RETURN
NC = MIN0 (129,NCHARS)
NWORD5 = NC*4
J = 1
DO 110 I = 1,NWORD5*4
UNPAKD(I) = PACKED(J)
UNPAKD(I+1) = LBLANK
UNPAKD(I+2) = LBLANK
UNPAKD(I+3) = LBLANK
110 CONTINUE
RETURN IF NCHARS IS LE ZERO
SET NC=NUMBER OF CHARS TO BE DECODED
=====

```

```

110 J = J+1
C
C      CHECK UNPAKD ARRAY AND SET NCHMTB
C      BASED ON TRAILING BLANKS FOUND
C
      DO 200 A = 1, NWORDS, 4
      NN = NWORDS - N - 2
      LBYTE = UNPAKD(NN)
      IF (LBYTE .NE. 1) GO TO 210
200 CONTINUE
210 NCHMTB = (NN + 3) / 4
      RETURN
      ENC
C
C      SUBROUTINE DATA - SUPPLIES THE INITIAL GUESSES WITH A FILE
C
C      SUBROUTINE DATA(X,N,N1,NE1)
C      IMPLICIT REAL*8(A-H,O-Z)
C      DIMENSION X(N)
C
C      PREDEFINED INITIAL GUESS
C      X(1) = 1.1
C      X(2) = 0.9
C      X(3) = -1.1
C      X(4) = 1.1
C      X(5) = 1.1
C      X(6) = -0.9
C      X(7) = -1.1
C      X(8) = -0.9
C      X(9) = 0.45
C      X(10) = 0.55
C      X(11) = -1.8
C      X(12) = -2.2
C      X(13) = 0.45
C      X(14) = -0.55
C      X(15) = -1.8
C      X(16) = -2.2
C
C      X(17) = 0.225
C      X(18) = 0.275
C      X(19) = -2.8
C      X(20) = 3.2
C      X(21) = 0.225
C      X(22) = 0.275
C      X(23) = -3.8
C      X(24) = -3.2

```

```

PROJ C570
PROJ C580
PROJ C590
PROJ C600
PROJ C610
PROJ C620
PROJ C630
PROJ C640
PROJ C650
PROJ C660
PROJ C670
PROJ C680
PROJ C690
PROJ C700
PROJ C710
PROJ C720
PROJ C730
PROJ C740
PROJ C750
PROJ C760
PROJ C770
PROJ C780
PROJ C790
PROJ C800
PROJ C810
PROJ C820
PROJ C830
PROJ C840
PROJ C850
PROJ C860
PROJ C870
PROJ C880
PROJ C890
PROJ C900
PROJ C910
PROJ C920
PROJ C930
PROJ C940
PROJ C950
PROJ C960
PROJ C970
PROJ C980
PROJ C990
PROJ C1000
PROJ C1010
PROJ C1020
PROJ C1030
PROJ C1040

```



PROJ 1C50  
PROJ 1C60

RETURN  
ENC

APPENDIX C  
DATA SIGNAL PLOTS

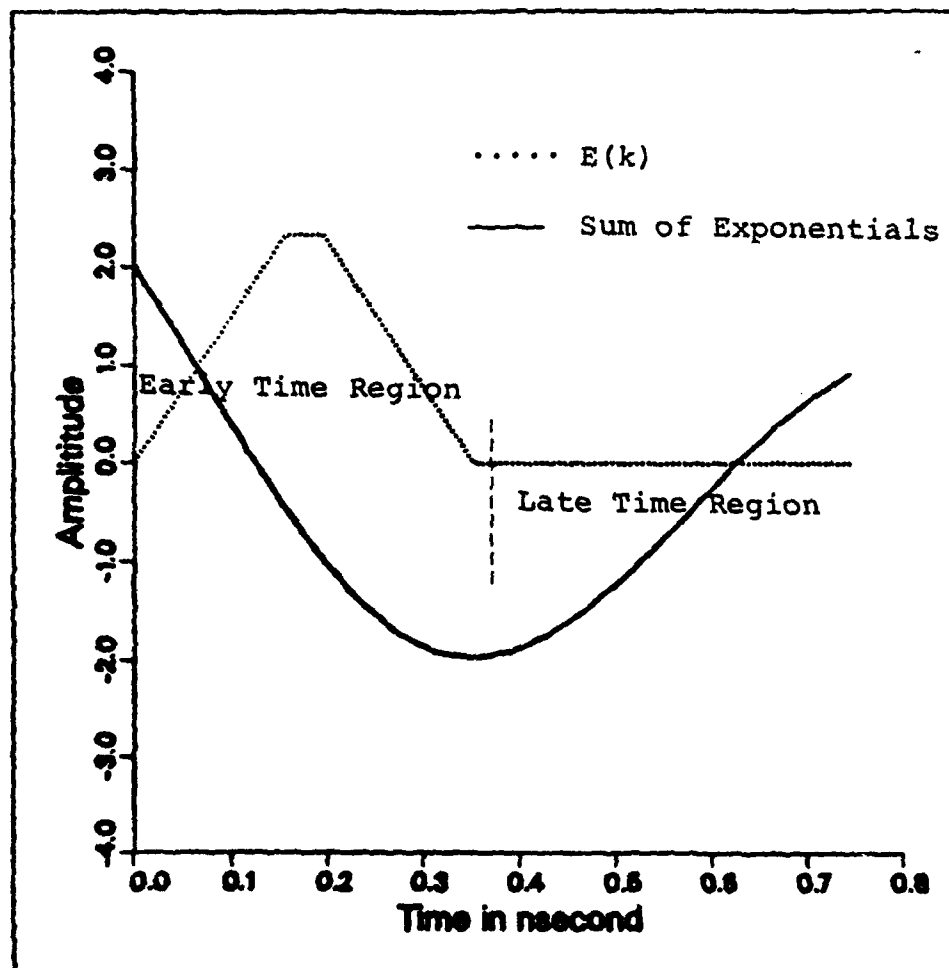


Figure C.1. Decomposition of Signal 1  
(Noise Free)

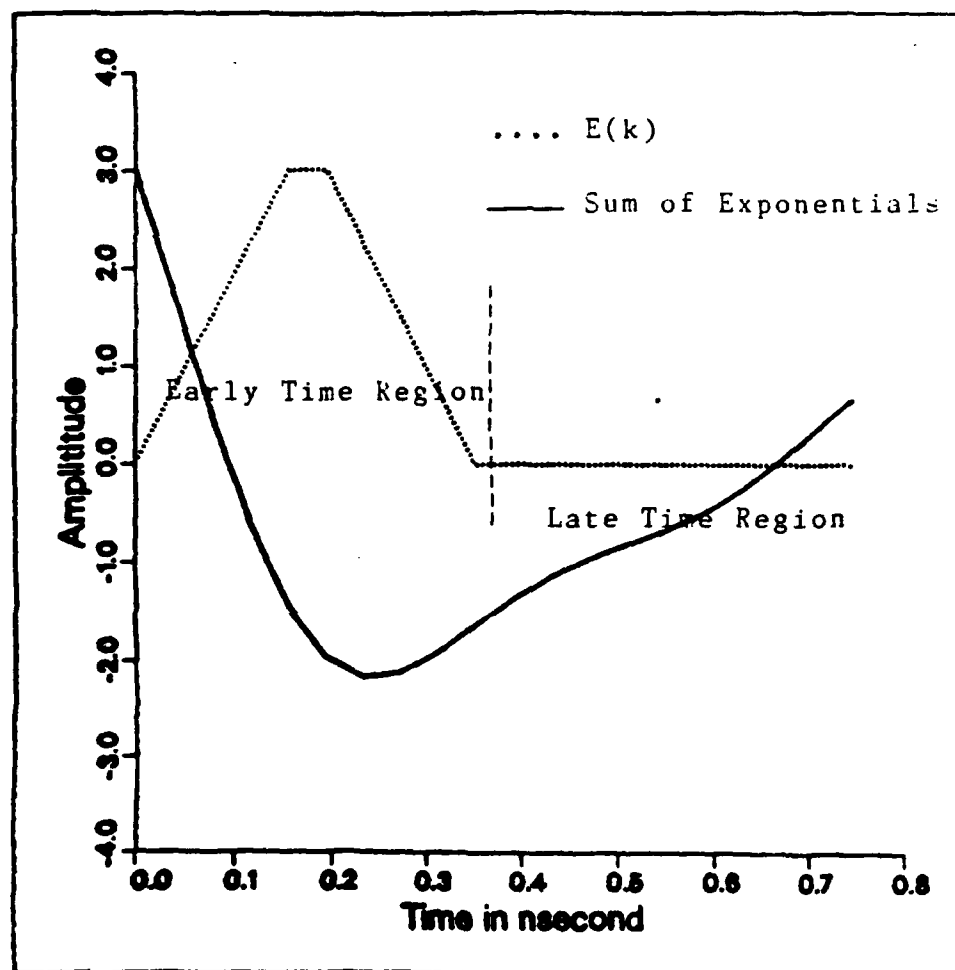


Figure C.2. Decomposition of Signal 1  
(Noise Free)

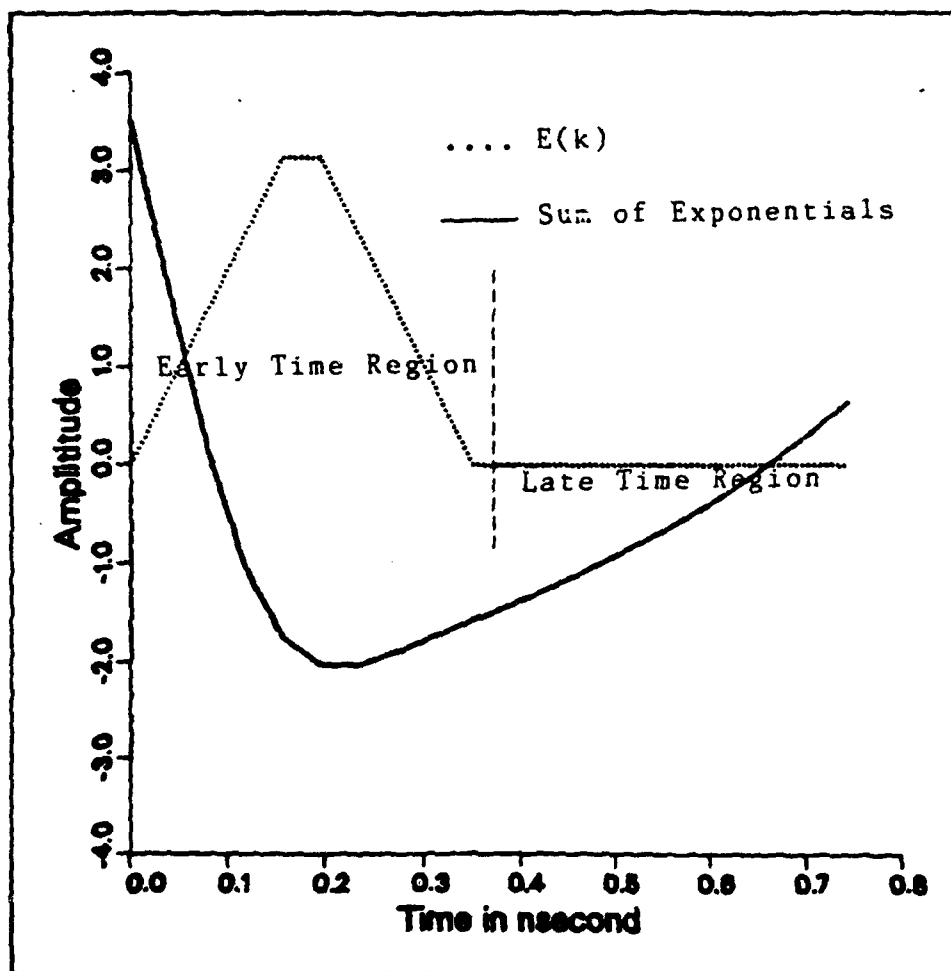


Figure C.3. Decomposition of Signal 3  
(Noise Free)

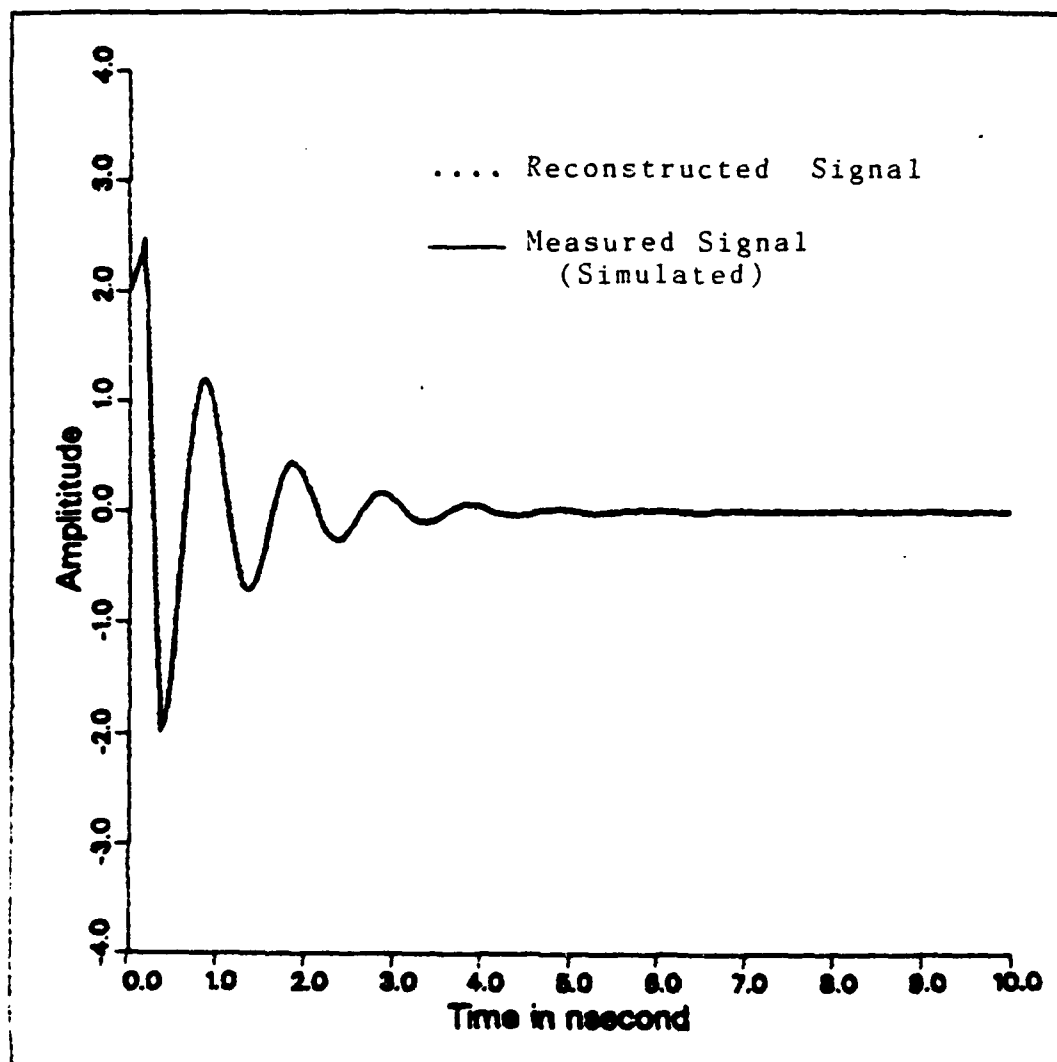


Figure C.4. Reconstruction of Signal 1 from The  
Computed Poles and Residues(SNR=30db)

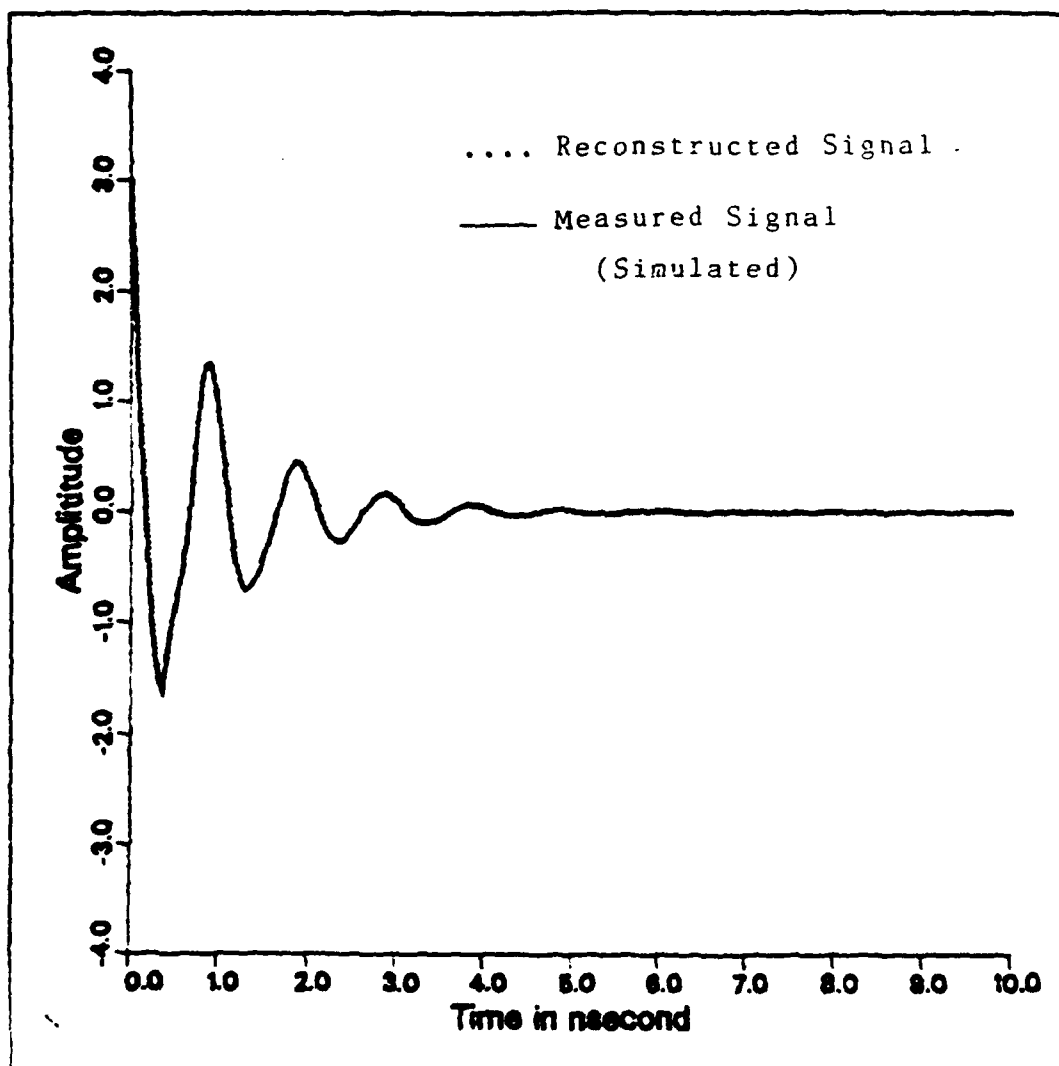


Figure C.5. Reconstruction of Signal 2 from The  
Computed Poles and Residues(SNR=30db)

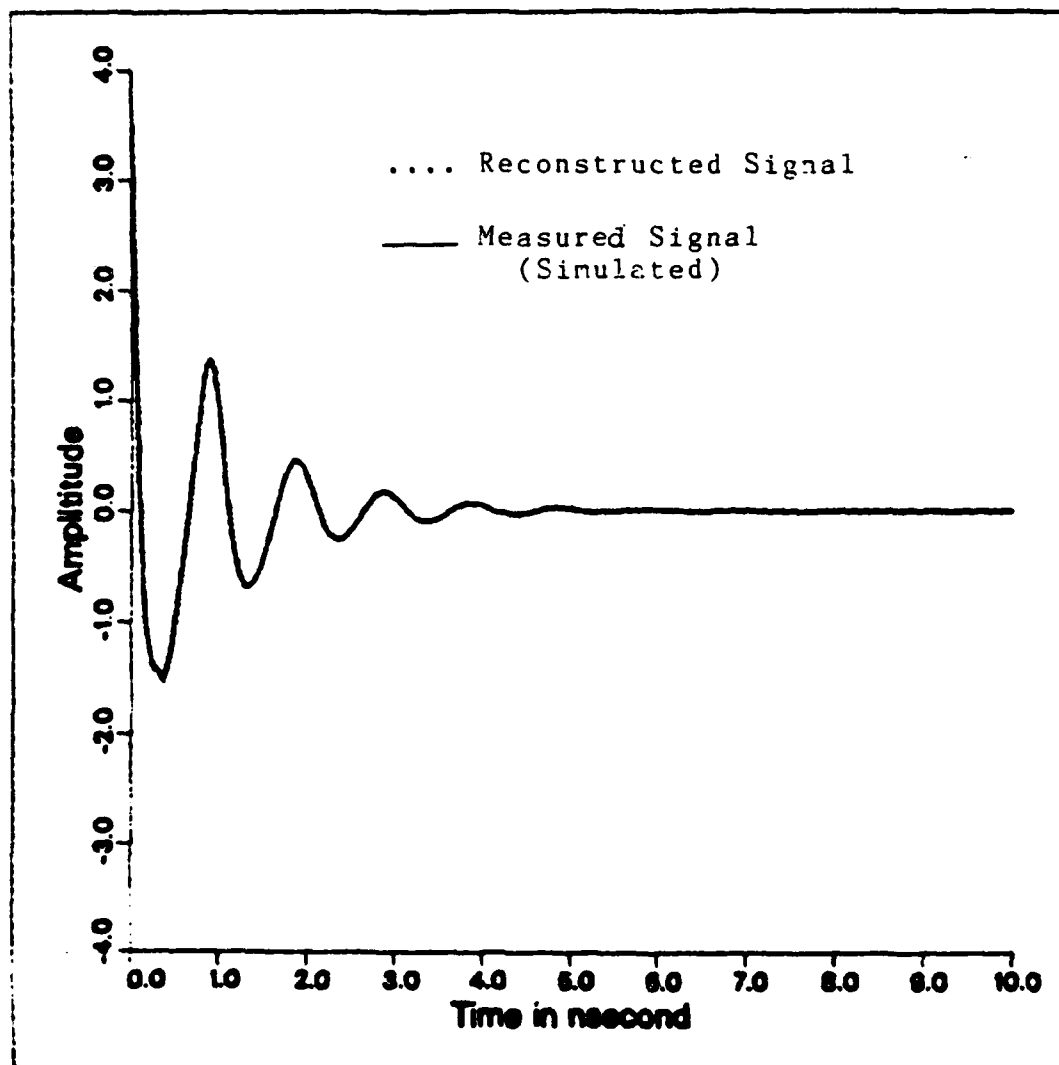


Figure C.6. Reconstruction of Signal 3 from The  
Computed Poles and Residues(SNR=30db)

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